SONY®

Color Camera Module

Technical Manual

FCB-ER8550/8530 FCB-CR8550/8530



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Precautions

Software

Use of the demonstration software developed by Sony Corporation or use of the software with customer developed application software may damage hardware, the application program or the camera. Sony Corporation is not liable for any damages under these conditions.

Operation

Start the camera control software on your computer after you turn on the camera and the image is displayed.

Operation and storage locations

Do not shoot images that are extremely bright (e.g., light sources, the sun, etc.) for long periods of time. Do not use or store the camera in the following extreme conditions:

- Extremely hot or cold places (operating temperature –5 °C to +60 °C (23 °F to 140 °F))
- Close to generators of powerful electromagnetic radiation such as radio or TV transmitters
- Where it is subject to fluorescent light reflections
- Where it is subject to unstable (flickering, etc.) lighting conditions
- Where it is subject to strong vibration
- Where it is subject to radiation from laser beams

Care of the unit

Remove dust or dirt on the surface of the lens with a blower (commercially available).

Other

- Design and specifications are subject to change without notice.
- Do not apply excessive voltage. (Use only the specified voltage.) Otherwise, you may get an electric shock or a fire may occur.
- The CMOS image sensor and IC included in this camera may break if exposed to static electricity. When directly handling this camera, wear an antistatic strap, spread a conductive sheet or similar item under your workbench, and take measures to eliminate static electricity.

• In case of abnormal operation, contact your authorized Sony dealer or the store where you purchased the product.

Handling precautions

- When handling this unit, be careful not to apply an excessive load to all portions of the unit except for the sheet-metal cover. Otherwise, it may result in a failure.
- This unit is designed to be built in the housing. Therefore, take measures to prevent the unit from receiving the intense light such as sunlight directly from the direction other than the front side. Otherwise, it may cause the image quality degradation.

Phenomena specific to CMOS image sensors

The following phenomena that may appear in images are specific to CMOS image sensors. They do not indicate malfunctions.

Rolling shutter

As CMOS image sensors use shutters that capture images line-by-line, there is a slight time difference between the top and bottom of an image. As a result, images may appear skewed if the camera is moved.

White flecks

Although the CMOS image sensors are produced with high-precision technologies, fine white flecks may be generated on the screen in rare cases, caused by cosmic rays, etc.

This is related to the principle of CMOS image sensors and is not a malfunction.

The white flecks especially tend to be seen in the following cases:

- when operating at a high environmental temperature
- when you have raised the master gain (sensitivity)
- when operating in Slow-Shutter mode

Aliasing

When fine patterns, stripes, or lines are shot, they may appear jagged or flicker.



Notes on incorporating a camera

When incorporating a camera on a device that turns ON/OFF 3 times or more a day on average, please confirm the temperature in the set using communication command 'CAM_TempInq' (VISCA) or 'CAM_Temperature' (PTP).

Please release heat until the increased temperature inside the set at the moment the set turns on reduces until it is stable at 12 °C or below.

Phenomena Specific to Lenses Ghosting

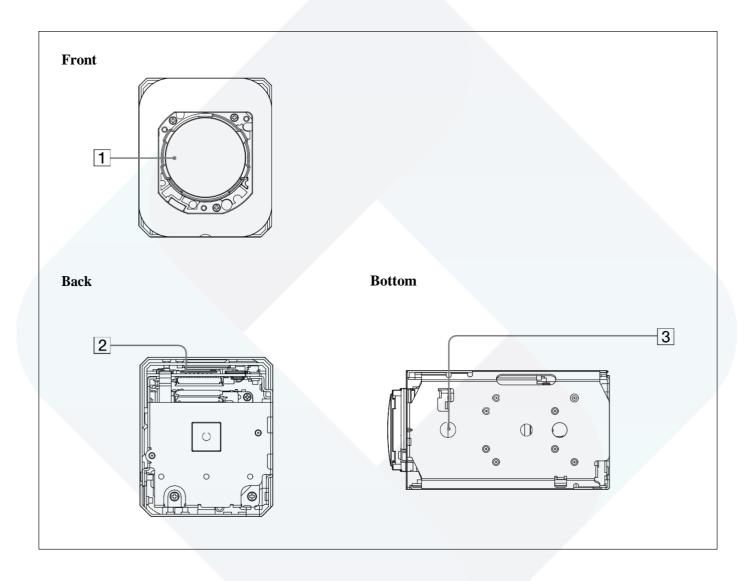
If a strong light source (e.g., the sun) exists near the incidence angle of the lens, bright spots may appear in the image due to diffuse reflection within the lens.

About the trademark

- "Exmor R" and "StableZoom" are trademarks of Sony Corporation.
- The terms HDMI and HDMI High-Definition Multimedia Interface, and the HDMI Logo are trademarks or registered trademarks of HDMI Licensing Administrator, Inc. in the United States and other countries.



Locations of Controls



- · Lens
- · CN1701 connector
- Tripod screw hole

When a tripod is used, please use 6 mm ($^{1}/_{4}$ in.) or less screw to attach it to the camera. Also, please be sure to attach the tripod securely.



Basic Functions

Overview of Functions

The camera control is performed by VISCA and PTP commands. For the camera control by PTP, refer to "Camera control PTP".

In general

• Power On/Off

Powers the camera on and off.

Although the screen is set non-displayed when the power is off, the camera is able to accept VISCA Command.

• I/F Clear

Clears the Command buffer of the FCB camera.

• Address Set

VISCA is a protocol, which normally supports a daisy chain of up to seven connected cameras via RS-232C interface. In such cases, the address set command can be used to assign addresses from 1 to 7 to each of the seven cameras, allowing you to control the seven cameras with the same personal computer.

Although the FCB camera does not support direct connection of cameras in a daisy chain, be sure to use the address set command to set the address whenever a camera is connected for the first time.

• ID Write

Sets the camera ID.

Mute

Blanks the screen and sends out a synchronizing signal.

• Lens Initialize

Initializes the zoom and focus of the lens. Even when power is turned on, it initializes the zoom and the focus.

• APR (Auto Pixel Restoration)

During operation of the FBC camera, the temperature of the set rises and white flecks may be generated on the CMOS image sensor.

The APR detects and corrects the white flecks, making them unnoticeable.

The detection function of the APR needs to be done while white flecks are generating.

If white flecks are not being generated, such as when the temperature of the camera is not high immediately after the set turns on, previously generated white flecks cannot be detected even if the APR is used. Therefore, please be sure to use the APR while white flecks are generating.

By turning on the APR and turning the power OFF/ON, white flecks are detected and corrected, and then recorded in the set.

Please be sure to turn "APR" to OFF when the APR correction is completed. The correction data is maintained even if "APR" is OFF.

Zoom

The FCB camera incorporates a $20\times$ optical zoom lens combined with a digital zoom function; this camera allows you to zoom up to $240\times$.

• Optical $20 \times$, f = 4.4 mm to 88.0 mm (F 2.0 to F 3.8)

The zoom magnification can be set in the following methods.

Using Standard Mode Using Variable Mode

There are eight levels of zoom speed.

In these standard and variable modes, it is necessary to send Stop Command to stop the zoom operation.

Direct Mode

Setting the zoom position enables quick movement to the designated position.

Digital Zoom

There are three types of zoom modes; OFF, combined mode and separate mode.

Combined Mode

This is the previously existing zoom method. After the optical zoom has reached its



maximum level, the camera switches to Digital Zoom Mode.

Separate Mode

In this mode, Optical Zoom and Digital Zoom can be operated separately. You can use digital zoom magnification at any time from within any level of optical magnification.

In the combined mode, the digital zoom range can be set.

Super Resolution Zoom

Through the use of "all pixel super resolution technology" developed by Sony Corporation, this product provides superior images while maintaining the resolution without degrading image quality, even when magnified. By combining with optical zoom $20\times$, zoom is achieved up to $30\times$ in 4K and $40\times$ in FHD.

About Continuous Zoom Position Reply

With ZoomDirect mode, or when zooming according to a preset, the camera outputs zoom position data when Continues Zoom Position Reply is set to On via a command

Continues Zoom Position Reply: y0 07 04 69 0p 0p 0q 0q 0q 0q FF

pp: D-Zoom Position qqqq: Zoom Position

Focus

Focus has the following modes.

• Auto Focus Mode

The Auto Focus (AF) function automatically adjusts the focus position to maximise the high frequency content of the picture in a center measurement area, taking into consideration the high luminance and strong contrast components.

The minimum focus distance is 80 mm at the optical wide end and 800 mm at the optical tele end.

- Normal AF Mode

This is the normal mode for AF operations.

- Interval AF Mode

The mode used for AF movements carried out at particular intervals. The time intervals for AF movements and for the timing of the stops can be set in one-second increments using the Set Time Command. The initial setting for both is set to 5 seconds.

- Zoom Trigger Mode

When zoom position is changed, it becomes AF mode during the pre-set value (initial setting is set to 5 seconds). Then it stops.

• AF Sensitivity

The switching of AF sensitivity can be set.

- Normal

Reaches the highest focus speed quickly. Use this when shooting a subject that moves frequently. Usually, this is the most appropriate mode.

- Low

Improves the stability of the focus. When the lighting level is low, the AF function does not take effect, even though the brightness varies, contributing to a stable image.

• Manual Focus Mode

Manual Focus has both a Standard Mode and a Variable Mode. Standard Mode focuses at a fixed rate of speed. Variable Mode has eight speed levels.

In these standard and variable modes, it is necessary to send Stop Command to stop the zoom operation.

• One Push Trigger Mode

When a Trigger Command is sent, the lens moves to adjust the focus for the subject. The focus lens then holds that position until the next Trigger Command is input.

• Near Limit

Can be set in a range from $1000 (\infty)$ to F000 (80 mm). Initial setting: B000h (35 cm)

• Spot focus mode

The spot focus mode allows you to focus on a specific portion of the subject. This mode is used when it is difficult to focus on the subject by using the normal auto focus, and so on. The focusing spot is specified by the area of the entire screen divided into 16-split both vertically and horizontally.

White Balance (WB)

White Balance has the following modes.

Auto

This mode computes the white balance value output using color information from the entire screen. It outputs the proper value using the color temperature radiating from a black subject based on a range of values from 2500K to 7500K.

This mode is the initial setting.

• ATW

Auto Tracing White balance (2000K to 10000K)

Indoor

3200K Base Mode

Outdoor

5800K Base Mode

One Push WB

The One Push White Balance mode is a fixed white balance mode that may be automatically readjusted only at the request of the user (One Push Trigger), assuming that a white subject, in correct lighting



conditions, and occupying more than 1/2 of the image, is submitted to the camera.

One Push White Balance data is lost when the power is turned off. If the power is turned off, reset One Push White Balance.

• Manual WB

This is a mode that enables you to manually set the control of R and B gain up to 256 steps.

Outdoor Auto

This is an auto white balance mode specifically for outdoors. It allows you to capture images with natural white balance in the morning and evening.

• Sodium Vapor Lamp Auto

This is an auto white balance mode that is compatible with sodium vapor lamps.

• Sodium Vapor Lamp

This is a fixed white balance mode specifically for sodium vapor lamps.

Sodium Vapor Lamp Outdoor Auto

This is an auto white balance mode specifically for outdoors, which is compatible with sodium vapor lamps.

Note

High-pressure sodium lamps are supported. Proper white balance may not be captured for some subjects when using low-pressure sodium lamps.

Auto Exposure Mode (AE)

A variety of AE functions are available for optimal output of subjects in lighting conditions that range from low to high.

• Full Auto

Iris, Gain and Shutter Speed can be set automatically.

• Gain Limit Setting

The gain limit can be set at Full Auto, Shutter Priority, Iris Priority, Bright, Spot Exposure and Manual in AE mode. Use this setting when you want to obtain images with a focus on the signal-to-noise ratio.

• Shutter Priority 1)

Adjust with Variable Shutter Speed (1/1 to 1/10,000 sec., 16 high-speed shutter speeds plus 12 low-speed shutter speeds), Auto Iris and Gain.

1) Flicker in the East Japan area (50 Hz power supply frequency) can be eliminated by setting shutter to 1/100s.

• Iris Priority

Adjust with Variable Iris (F2.0 to Close, 22 steps), Auto Gain and Shutter speed

• Gain

Adjust with Variable Gain (0 to 36 dB, 13 steps, 38 steps on High sensitivity mode), Auto Iris and Shutter speed

Manual

Adjust with Variable Shutter speed, Iris and Gain

Bright

Adjust with Variable Iris and Gain (Close to F2.0, 34 steps and High Sensitivity Mode at 38 steps)

AE – Shutter Priority

The shutter speed can be set freely by the user to a total of 28 steps – 16 high speeds and 12 low speeds. When the slow shutter is set, the speed can be adjusted according to subject brightness. The picture output is read at a normal rate from the memory. The memory is updated at a low rate from the CMOS. AF following capability is lowered and also the number of frame to be displayed is decreased.

In high speed mode, the shutter speed can be set up to 1/10,000s. The iris and gain are set automatically, according to the brightness of the subject.

	T		
Data	59.94/29.97 mode	50/25 mode	23.98 mode
21	1/10000	1/10000	1/10000
20	1/6000	1/6000	1/4800
1F	1/4000	1/3500	1/2400
1E	1/3000	1/2500	1/1200
1D	1/2000	1/1750	1/576
1C	1/1500	1/1250	1/400
1B	1/1000	1/1000	1/288
1A	1/725	1/600	1/200
19	1/500	1/425	1/192
18	1/350	1/300	1/144
17	1/250	1/215	1/120
16	1/180	1/150	1/100
15	1/125	1/120	1/96
14	1/100	1/100	1/60
13	1/90	1/60	1/50
12	1/60	1/50	1/48
11	1/50	1/30	1/40
10	1/30	1/25	1/25
0F	1/20	1/20	1/24
0E	1/15	1/15	1/20
0D	1/10	1/12	1/12
0C	1/8	1/8	1/8
0B	1/6	1/6	1/6
0A	1/4	1/4	1/4
9	1/3	1/3	1/3
8	1/2	1/2	1/2
7	2/3	2/3	2/3
6	1/1	1/1	1/1



AE - Iris Priority

The iris can be set freely by the user in 22 steps between F2 and Close.

The gain and shutter speed are set automatically according to the brightness of the subject.

Data	Setting value	Data	Setting value
19	F2	0E	F5.2
18	F2.2	0D	F5.6
17	F2.4	0C	F6.2
16	F2.6	0B	F6.8
15	F2.8	0A	F7.3
14	F3.1	09	F8
13	F3.4	08	F8.7
12	F3.7	07	F9.6
11	F4	06	F10
10	F4.4	05	F11
0F	F4.8	00	CLOSE

AE - Manual

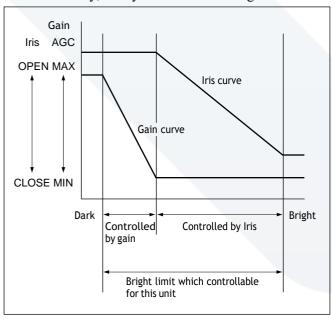
The shutter speed (28 steps), iris (22 steps) and gain (17 steps) can be set freely by the user.

AE - Bright

The bright control function adjusts both gain and iris using an internal algorithm, according to a brightness level freely set by the user. Exposure is controlled by gain when dark, and by iris when bright.

As both gain and iris are fixed, this mode is used when exposing at a fixed camera sensitivity. When switching from Full Auto or Shutter Priority Mode to Bright Mode, the current status will be retained for a short period of time.

Only when the AE mode is set to "Full Auto" or "Shutter Priority," can you switch it to "Bright."



Data	Iris	Gain	Data	Iris	Gain
29*	F2.0	48 dB	16	F2.6	0 dB
28*	F2.0	45 dB	15	F2.8	0 dB
27*	F2.0	42 dB	14	F3.1	0 dB
26*	F2.0	39 dB	13	F3.4	0 dB
25	F2.0	36 dB	12	F3.7	0 dB
24	F2.0	33 dB	11	F4	0 dB
23	F2.0	30 dB	10	F4.4	0 dB
22	F2.0	27 dB	0F	F4.8	0 dB
21	F2.0	24 dB	0E	F5.2	0 dB
20	F2.0	21 dB	0D	F5.6	0 dB
1F	F2.0	18 dB	0C	F6.2	0 dB
1E	F2.0	15 dB	0B	F6.8	0 dB
1D	F2.0	12 dB	0A	F7.3	0 dB
1C	F2.0	9 dB	9	F8.0	0 dB
1B	F2.0	6 dB	8	F8.7	0 dB
1A	F2.0	0 dB	7	F9.6	0 dB
19	F2.0	0 dB	6	F10	0 dB
18	F2.2	0 dB	5	F11	0 dB
17	F2.4	0 dB	00	CLOSE	0 dB

^{*}When high sensitivity mode is on.

When switching from the Shutter Priority mode to the Bright mode, the shutter speed set in the Shutter Priority mode is maintained.

Gain Limit Setting

The gain limit can be set at the Full Auto, Shutter Priority and Iris Priority of the Auto Exposure Mode. Use this setting when you want to obtain image in which signal-to-noise ratio is particularly important.

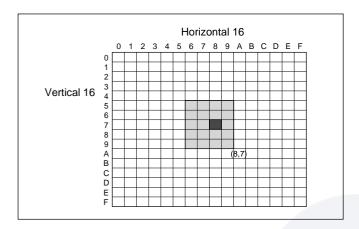
Gain Point Setting

Set the Gain Point in the middle between 0dB and gain limit. The shutter speed can be changed from the point when the set gain value is reached. When you want to obtain the motion-priority image, use this setting.

Spot Exposure Mode

In Full Auto AE, the level for the entire screen is computed and the optimum Auto Iris and Gain levels are determined. In Spot AE, a particular section of the subject can be designated, and then that portion of the image can be weighted and a value is computed so that the Iris and Gain can be optimized to obtain an image. For example, in an image with a lot of movement and with varying levels of brightness, portions without much change can be designated as such a "spot," and changes to the screen can be minimized in that area. As shown in the diagram below, a range of 16 blocks vertically and 16 blocks horizontally can be designated. The level is calculated by the value of the surrounding blocks (shaded) including the designated center block (black). The range of the Spot AE frame is fixed to 5 blocks vertically and 4 blocks horizontally.





Exposure Compensation

Exposure compensation is a function which offsets the internal reference brightness level used in the AE mode, by steps of 1.5 dB.

Data	Step	Setting value
0E	+7	+10.5 dB
0D	+6	+9 dB
0C	+5	+7.5 dB
0B	+4	+6 dB
0A	+3	+4.5 dB
09	+2	+3 dB
08	+1	+1.5 dB
07	0	0 dB
06	-1	−1.5 dB
05	-2	−3 dB
04	-3	-4.5 dB
03	-4	−6 dB
02	-5	−7.5 dB
01	-6	−9 dB
00	-7	−10.5 dB

Slow AE (Auto Exposure)

The slow AE Response function allows you to reduce the exposure response speed. Usually the camera is set up so that the optimum exposure can be obtained automatically within about 1 second. However, using the slow AE response function allows you to lengthen the auto exposure response speed from the initial setup speed (01h) to approx. 10 minutes (30h) (at normal shutter speed).

For example, with the normal setting (about 1 second), if the headlights of a car are caught by the camera, the camera automatically adjusts the exposure so that it can shoot a high-intensity subject (in this case, the headlights). As a result, images around the headlights, that is, the rest of the subject, except the headlights, becomes relatively dark, and poorly distinguished. However, using the slow AE function means the AE response speed will be slower, and response time will be longer. As a result, even if the camera catches a high-intensity subject (e.g., the headlights) for a moment, you can still easily distinguish the portions of the image surrounding the headlights.

High Resolution Mode

This mode enhances edges and produces higher definition images.

Aperture Control

Aperture control is a function which adjusts the edge enhancement of objects in the picture.

When it is set to Auto, the adjustment is performed automatically.

When it is set to Manual, you can adjust multiple setting items. Sometimes, the noise particle that is generated when the gain is increased becomes noticeable because its edge is enhanced by this function. In this case, lower the edge enhancement level or adjust the edge enhancement amount of noise by "Crispening".

Backlight Compensation

When the background of the subject is too bright, or when the subject is too dark due to shooting in the AE mode, back light compensation will make the subject appear clearer.

Visibility Enhancer (VE)

Depending on the imaging scene, the Visibility Enhancer function makes the darker part of a camera image brighter, and automatically correct brightness and contrast to show bright parts clearly.

Defog mode

When the surrounding area of the subject is foggy and low contrast, the defog mode will make the subject appear clearer.

You can select four levels for this function: OFF, Low, Middle and High.

Highlight Compensation (HLC)

HLC (highlight correction) is a function to adjust AE and AF, and to perform the masking of light area as required when a high intensity spot light is detected. It allows you to easily read the number of vehicles and number plate in the indoor parking area or in the outdoor during the night.



Maximum Shutter Limit

The brighter the object is, the shutter speed will increase. This is the function to set the upper limitation on the shutter speed. This will help to make images smooth with less inconsistent motions when you shoot bright objects.

Minimum Shutter Limit

When the subject becomes dark, the shutter speed becomes slow and the gain is increased. This is a function to put a limit on the shutter speed. It prevents the camera shake when you shoot a moving subject in a dark place.

Noise Reduction (NR)

The NR function removes noise (both random and non-random) to provide clearer images.

This function has six steps: levels 1 to 5, plus off.

The NR effect is applied in levels based on the gain, and this setting value determines the limit of the effect. In bright conditions, changing the NR level will not have an effect.

When it is set to level 7Fh, you can set NR of 2D/3D individually.

High Sensitivity Mode

In this mode, the maximum gain increases, enabling to obtain a brighter output even in a darker environment. However, if the gain reaches high level, the image will have a large amount of noise.

Variable Gamma Mode

Standard (00h), straight gamma (01h), 512 pattern (02h) are available for setting.

Gamma Offset

You can set the brightness from -16 (00h) to +64 (40h) in each mode of the variable gamma mode.

Temperature Reading Function

The conversion value (hex) of the temperature sensor built into to the camera can be read by using a query command. The conversion value has an error of ± 3 C, and because the temperature sensor is inside the camera, this value is not the ambient temperature. Use it as a reference value.

Slow Shutter On/Off

When set to "On," the slow shutter functions automatically when the light darkens. This setting is available only when the AE mode is set to "Full Auto." The initial setting is "Auto Slow Shutter Off."

Low-Illumination Chroma Suppress Mode

You can configure a chroma suppress mode for lowillumination conditions. This can be useful when color noise is particularly noticeable in such conditions. Four levels (disabled and three levels) are available for the low-illumination chroma suppress mode.

ICR (IR Cut-Removable) Mode

The IR Cut-Filter installed in front of the CMOS image sensor can be engaged or disengaged by the mechanical structure. The sensitivity in the infrared region is increased by disengaging the IR Cut-Filter, allowing the camera to capture the image in darker places. When the auto ICR mode is set to On, the image becomes black and white.

Custom Color Gain

You can configure the color gain. Use this setting when bright color is particularly important.

The initial setting 100% (4h) can be set to range from approx. 60% (0h) to 200% (Eh) with 15 stages.

Custom Color Phase

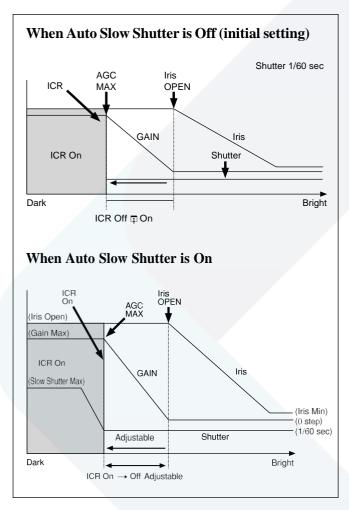
You can configure the color phase. The initial setting 0 degrees (7h) is adjustable between approx. -14 degrees (0h) to +14 degrees (Eh), in 15 increments.



Auto ICR Mode

Auto ICR Mode automatically switches the settings needed for attaching or removing the IR Cut Filter. With a set level of darkness, the IR Cut Filter is automatically disabled (ICR On), and the infrared sensitivity is increased. With a set level of brightness, the IR Cut Filter is automatically enabled (ICR Off). Also, on systems equipped with an IR light, the internal data of the camera is used to make the proper decisions to avoid malfunctions.

Auto ICR Mode operates with the AE Full Auto setting.



Note

Depending on the information such as brightness, etc., in the On/ Off settings condition, a malfunction may occur when the subjects largely consisting of blue and green colors are taken.

Camera ID

The ID can be set up to 65,536 (0000h to FFFFh). As this will be memorized in the nonvolatile memory inside, data will be saved.

Picture Effect

It consists of the following function.

• Black & White: Monochrome Image

Image stabilizer

When the image stabilizer function is set to On, you can obtain the image with less screen blur caused by shaking and so on. The correction effect can be achieved at the vibration frequency around 10 Hz. The image stabilizer function uses the digital zoom method. Although there are changes in the angle of view and resolution, the sensitivity is maintained.

Note

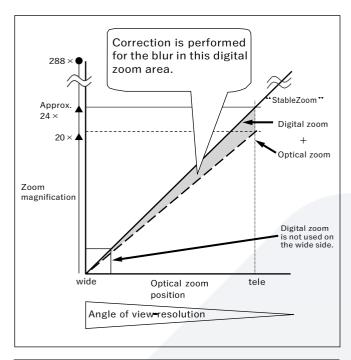
The image stabilizer function may not work under the environment of high frequency vibration components. When using the camera under such environment, set the image stabilizer function to Off.

"StableZoom"

"StableZoom" is a function to perform correction using the image stabilizer function according to the zoom magnification and zoom the image up to approx. 24× smoothly by combining the optical zoom with the digital zoom. By zooming the image furthermore using the digital zoom, the image is zoomed up to 288×. On the wide side, the image without the deterioration in resolution can be obtained because the digital zoom is not used. On the other hand, the correction effect by the image stabilizer function is maximized on the tele side, reducing the blur.

"StableZoom" can be set to On/Off by the register setting.





Others

E-FLIP

This function reverses the video output from the camera vertically and horizontally.

LR Reverse

This function reverses the video output from the camera horizontally.

Freeze

This function captures an image in the field memory of the camera so that this image can be output continuously.

Because communication inside the camera is based on V cycle, the captured image is always the one 3V to 4Vs after the sending of a Command. Thus, you can not specify a time period after sending EVEN, ODD or a Command.

Electronic Pan/Tilt

In 4K (3840 \times 2160) mode, crop the image at the designated position to Full HD (1920 \times 1080) and display.

You can specify the central coordinate of cropped images by commands. Cropped sizes cannot be changed as it is fixed to FHD.

Memory (Position preset)

Using the position preset function, 16 sets of camera shooting conditions can be stored and recalled. This function allows you to achieve the desired status instantly, even without adjusting the following items each time.

- Zoom Position
- Digital Zoom On/Off/Super Resolution Zoom
- Focus Auto/Manual
- Focus Position
- AE Mode
- Shutter control parameters
- Bright Control
- Iris control parameters
- Gain control parameters
- Exposure Compensation On/Off
- Exposure Level
- Backlight Compensation On/Off
- Slow Shutter On/Off
- White Balance
- R/B Gain
- Aperture Control
- ICR On/Off
- Defog

Custom Preset

As with the position preset function, the camera shooting conditions can be stored and recalled. The settings are recalled when the power is turned on. For setting items, see the "Initial Settings, Custom Preset and Backup" section on page 24.

User Memory Area

A user area of 16 bytes allows you to write data, such as an ID for each customer, data for each system, and so on, freely.

Note

Rewriting of memory is not unlimited. Be careful to avoid using the memory area for such as unnecessary tasks as rewriting the contents of the memory for every operation.

Register Setting

The camera's initial settings can be changed by the register setting command.

Register Setting Command:

8x 01 04 24 mm 0p 0q FF

mm: Register No. (=00 to 7F)

pq: Register Value (=00 to FF)

Register Inquiry Command:

8x 09 04 24 mm FF

mm: Register No.

y0 50 0p 0p FF

pp: Register Value

(returned from the camera)

The register setting items and No. are as follows. For details, see "Register Setting" on page 55.

Baud Rate: 00

Communication speed can be changed.

Monitoring Mode: 72

The output mode can be set.



Zoom Limit: 50 (wide end), 51 (tele end)
The wide and tele zoom limits can be set.

D-Zoom Max: 52

The maximum digital zoom limit can be set (initial settinig is $12\times$).

FocusOffset: 55

Placing a dome cover in front of the camera may cause the focal distance of the camera to change. Especially at the Tele end, this effect exceeds the AF range, so focus cannot track, although it responds to changes in this value.

For details, see "Register Setting" on page 55.

Extended mode: 5F

ON/OFF can be set. (initial setting is OFF.) For details, see page 17.

Note

After changing the register setting, turn off the camera, then turn it on again.

Privacy Zone Masking Settings

For details, see page 15.

Title Display

- You can set a title of up to 11 lines. One line can contain up to 20 characters.
- You can set display on/off, the horizontal position of the first character, blinking state and color for each line.
- The camera gives priority to a title display when the camera status is displayed on the relevant line. On the lines where a title is not set, the camera status is displayed.

Line Number	00h to 0Ah		
H-position	00h t	o 1Fh	
	00h	WHITE	
	01h	YELLOW	
	02h	VIOLET	
Color	03h	RED	
	04h	CYAN	
	05h	GREEN	
	06h	BLUE	
Blink	00h	Off	
	01h	On	

00	01	02	03	04	05	06	07
A	В	C	D	Е	F	G	Н
08	09	0A	0B	0C	0D	0E	0F
I	J	K	L	M	N	O	P
10	11	12	13	14	15	16	17
Q	R	S	T	U	V	W	X
18	19	1A	1B	1C	1D	1E	1F
Y	Z	&		?	!	1	2
20	21	22	23	24	25	26	27
3	4	5	6	7	8	9	0
28	29	2A	2B	2C	2D	2E	2F
À	È	Ì	Ò	Ù	Á	É	Í
30	31	32	33	34	35	36	37
Ó	Ú	Â	Ê	Ô	Æ		Ã
38	39	3A	3B	3C	3D	3E	3F
Õ	Ñ	Ç	В	Ä	Ϊ	Ö	Ü
40	41	42	43	44	45	46	47
Å	\$		¥		£	i	i
48	49	4A	4B	4C	4D	4E	4F
ø	,,	:	,		,	/	-



Privacy Zone Masking Function

Privacy Zone masking protects private objects and areas such as house windows, entrances, and exits which are within the camera's range of vision but not subject to surveillance.

Privacy zone masking can be masked on the monitor to protect privacy.

Features

- Mask can be set on up to 24 places according to Pan/ Tilt positions.
- Mask can be displayed on 8 places per screen simultaneously.
- Individual on/off zone masking settings.
- Two colors can be individually set for each of 24 privacy zones.
- Interlocking control with zooming.
- Interlocking control with Pan/Tilt.
- Non-interlocking control with Pan/Tilt.

Details of Setting Commands

Set Mask

Command: 8x 01 04 76 mm nn 0r 0r 0s 0s FF Parameters:

4	mm	Setting Mask		
		See "mm: Mask setting list" in "Parameters" on page 15.		
	nn	Selects new setting or resetting for the zone. See "nn:		
		Setting" in "Parameters" on page 15.		
	rr	Sets the half value "w" of the Mask Width.		
	SS	Sets the half value "h" of the Mask Height.		
		See "pp: x, qq: y, rr: w, ss: h" in "Parameters" on page 15.		

Comments: To set the mask, first display the object at the center of the screen. When "nn" is set to 1, the current Pan/Tilt/Zoom Position is recorded in internal memory.

When "nn" is set to 0, the Pan/Tilt/Zoom Position in memory is not changed.

Notes

- The tilt angle at which you can set the mask is between -70 to +70 degrees.
- It is recommended that you set the size to at least twice the size of the object (height and width).

Set Display

Command: 8x 01 04 77 pp pp pp pF FF

Parameter:

pp pp pp pp	Each 24 Privacy Zones corresponds to the BIT.
	See "pp pp pp pp: Mask bit" in "Parameters" on
	page 16.

Comments: Each of 24 Privacy zones can be switched on and off individually by a single VISCA Command. If you want to display a Privacy zone, you must set its bit to 1. If you do not want to display a Privacy zone, you must set its bit to 0.

Set Mask Color

Command: 8x 01 04 78 pp pp pp pp qq rr FF **Parameter:**

pp pp pp pp	Each 24 Privacy Zones correspond to the BIT.
	See "pp pp pp pp: Mask bit" in "Parameters" on
	page 16.
qq	Set the color code
rr	Set the color code. See "qq, rr: Color code" in
	"Parameters" on page 17.

Comments: Two different color masks can be chosen.

Two colors can be individually set for each of 24 privacy zones.

If the bit of parameter (pp pp pp pp) is set to "0", mask color will be "qq" color (Color code). If the bit of parameter (pp pp pp pp) is set to "1", the mask color will be "rr" color (Color code).

Example: 8x 01 04 78 00 00 00 03 00 07 FF

The mask color of Mask_A and Mask_B is White (color code 07h), and the mask color of the other Mask (C to X) is Black (color code 00h).

Set Pan Tilt Angle

Command: 8x 01 04 79 0p 0p 0p 0q 0q 0q FF

Parameter:

ppp	Pan Angle
qqq	Tilt Angle See "Setting pan/tilt angle" in "Parameters" on
	page 16.

Comments: Pan/Tilt angle settings are hexadecimal data.

The resolution of Pan/Tilt angle is 0.088 degrees.

Notes

- When you set the pan/tilt angle, locate the pan/tilt position at the center point of the FCB camera's position.
- If you set the pan/tilt angle or zoom the camera, a bigger mask will be displayed for about one second.



Set PTZ Mask

Command: 8x 01 04 7B mm 0p 0p 0p 0q 0q 0q 0r 0r 0r 0r FF

Parameter:

mm	Setting Mask	
	See "mm: Mask setting list" in "Parameters" on page 16.	
ppp	Pan Angle (000 to FFF)	
	See "Setting pan/tilt angle" in "Parameters" on page 16.	
qqq	q Tilt Angle (000 to FFF)	
	See "Setting pan/tilt angle" in "Parameters" on page 16.	
rrrr	Zoom Position (000 to 4000)	
	See "Zoom Ratio and Zoom Position (for reference)" on	
	page 53.	

Comments: Mask can be set at the desired position by setting the pan tilt angle and zoom position using this command. The set value can be input by hexadecimal number.

Note

Privacy mask zone follows the change of angle of view according to zoom. However, the follow might be delayed for a moment if there is any big change, such as when using D-Zoom or E-FLIP.

Non Interlock Mask

Command: 8x 01 04 6F mm 0p 0p 0q 0q 0r 0r 0s 0s FF

Parameters:

mm	Setting Mask
	See "mm: Mask setting list" in "Parameters" on page 15.
pp	Sets the center position "x" of the Mask on screen.
qq	Sets the center position "y" of the Mask on screen.
rr	Sets the half value "w" of the Mask Width.
SS	Sets the half value "h" of the Mask Height.
	See "pp: x, qq: y, rr: w, ss: h" in "Parameters" on page 15.

Commands: Mask does not interlock with pan/tilt. The limitations of parameters are as follows. (hexadecimal representation)

x: ±50h w: ±50h y: ±2Dh h: ±2Dh

Note

When the Set Mask command and the Non Interlock Mask command are set to the same mask, the command set later becomes effective.

Parameters

mm: Mask setting list

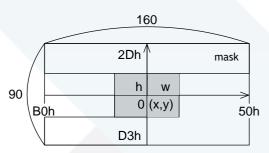
Mask Name	mm (Hex)
Mask_A	00h
Mask_B	01h
Mask_C	02h
Mask_D	03h
Mask_E	04h
Mask_F	05h
Mask_G	06h
Mask_H	07h
Mask_I	08h
Mask_J	09h
Mask_K	0Ah
Mask_L	0Bh

Mask Name	mm (Hex)
Mask_M	0Ch
Mask_N	0Dh
Mask_O	0Eh
Mask_P	0Fh
Mask_Q	10h
Mask_R	11h
Mask_S	12h
Mask_T	13h
Mask_U	14h
Mask_V	15h
Mask_W	16h
Mask_X	17h

nn:Setting

nn	Setting
00h	Resetting the zone size (the value of w,h)
	for the existing mask.
01h	Setting newly the zone size (the value of w,h).

pp: x, qq: y, rr: w, ss: h



Effective display area

note

The priority order of the mask display is in the sequence from A (highest) to X (lowest).

When you set the parameters of masks non-sequentially, it is recommended that you set the mask whose priority order is higher, first.

pp pp pp pp: Mask bit

	pp								pp							
bit	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Mask	-	ı	X	W	V	U	T	S	ı	ı	R	Q	P	О	N	M

Ī								pp									
Ī	bit	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Ī	Mask	1	1	L	K	J	I	Н	G	-	-	F	Е	D	C	В	A

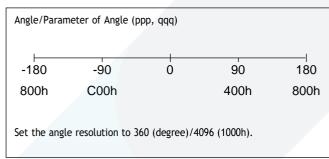
The "-" must be "0".

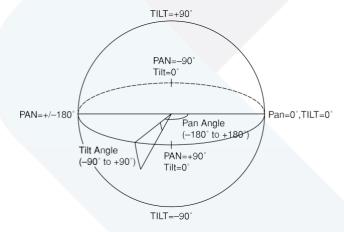


qq, rr: Color code

Mask (color)	Code (qq, rr)	Translucence (qq, rr)
Black	00 h	10 h
Gray1	01 h	11 h
Gray2	02 h	12 h
Gray3	03 h	13 h
Gray4	04 h	14 h
Gray5	05 h	15 h
Gray6	06 h	16 h
White	07 h	17 h
Red	08 h	18 h
Green	09 h	19 h
Blue	0A h	1A h
Cyan	0B h	1B h
Yellow	0C h	1C h
Magenta	0D h	1D h
Mosaic		7F h

Setting pan/tilt angle





Extended Commands

Extended commands support the following functions (described previously).

Turn on this mode (for details, see "Extended Mode" in "Register Setting" on page 55) to enable the following functions.

• Exposure Compensation

The setting can be set in steps of approximately 0.2dB (-128 (00h) to approximately +127 (FFh)).

For details, see page 9.

Aperture Control

The setting can be set to 256 levels (00h to FFh). *For details, see page 10.*

Custom Color Gain

The initial setting is 100% (80h), and the setting can be set to 256 levels from approximately 0% (00h) to approximately 200% (FFh).

For details, see page 11.

Custom Color Phase

The initial setting is 0 degrees (80h), and the setting can be set to 256 levels from approximately -14 degrees (00h) to approximately +14 degrees (FFh).

For details, see page 11.

Auto ICR Mode

The setting of ICR ON→OFF threshold can be set when Auto ICR is on.

The setting range is 0 step (00h) to 255 step (FFh). The setting of ICR OFF→ON threshold (On Level) can be set when Auto ICR is on.

The setting range is 0 step (00h) to 28 step (1Ch). For details, see page 12.

Note

When the extended mode is Off, CMD_NOT_EXEC will be returned if you send the extended commands to the camera. When the extended mode is On, CMD_NOT_EXEC will be returned if you send the normal commands to the camera.



External synchronization function (FCB-ER8550)

External synchronization will start when you input synchronization signals to 15pin on CN1701. The possible external synchronization combinations are listed below:

Input External Signal	Т	NTSC	PAL		
format Camera Mode	1080/59.94i	1080/50i	1080/47.95i	Black burst	Black burst
3840×2160/29.97p	≕	×	×	=>	×
3840×2160/25p	×	≡ÿ	×	×	≕
3840×2160/23.98p	×	×	≕	×	×
1920×1080/59.94p	≕	×	×	=;	×
1920×1080/59.94i	≕	×	×	=;	×
1920×1080/50p	×	Ξ∛	×	×	=ÿ
1920×1080/50i	×	≡¥	×	×	≕
1920×1080/29.97p	≕	×	×	≕	×
1920×1080/25p	×	Ξ∛	×	×	=ÿ
1920×1080/23.98p	×	×	≕	×	×
1280×720/59.94p	≕	×	×	≕	×
1280×720/50p	×	Ξξ	×	×	≕
720×480/59.94p		×	×	=>>	×
720×576/50p	×	≕	×	×	Ξξ

External signal spec

• Tri-State SYNC: partial part of SMPTE 240M/274M

 NTSC Black burst: EBU N14/SMPTE RP-154/SMPTE 170M/SMPTE 318M

• PAL Black burst: ITU-R BT.470-6

The H Phase adoption function is not available.

Notes

- Once you input the external synchronization signal, do not change the settings until the state enters the external synchronization mode.
- If the external synchronization signal is not stable, the unit will not enter the external synchronization mode.
- In the cases below, images or data will be disordered and may malfunction.
 - if you input signals other than the allowed external synchronization signals.
 - -if you input external synchronization signals when the external synchronization is not supported.

About the firmware update

Overview

This document descries detailed operation for firmware update.

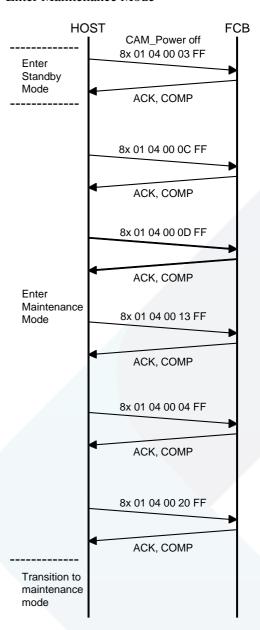
Serial Port Setting during maintenance mode

Communication Speed	115200 bps
Data bit	8 bit
Parity	None
Stop bit	1 bit
Flow control	None

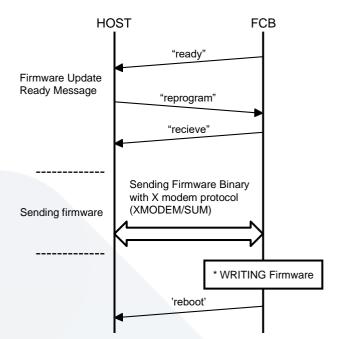


Update Procedure (UART)

Enter Maintenance Mode



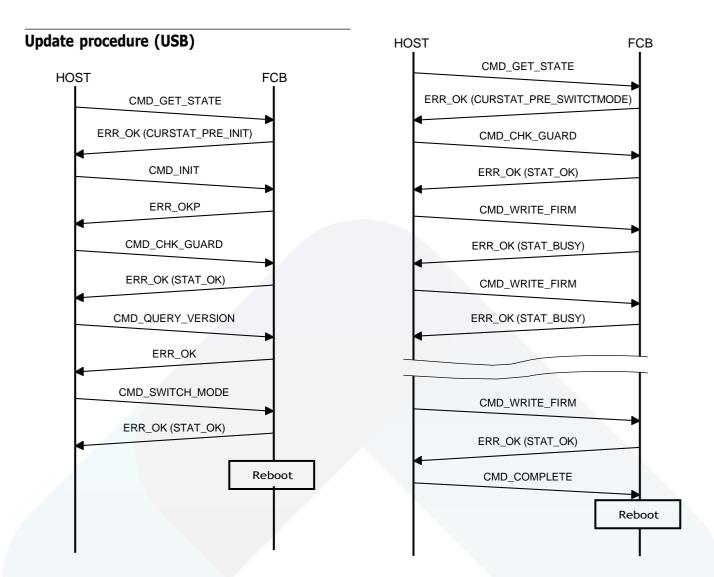
Maintenance Mode



* When power is off during this period, camera will be broken.

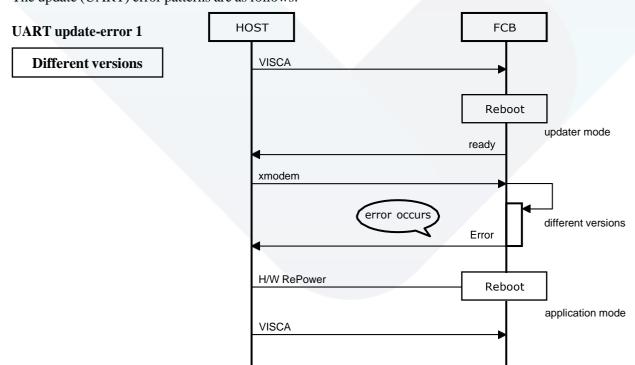
^{*} It takes approximately 14 seconds to transition to maintenance

^{*} When power is off during this period, camera will be broken.



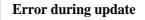
Error occurrence patterns

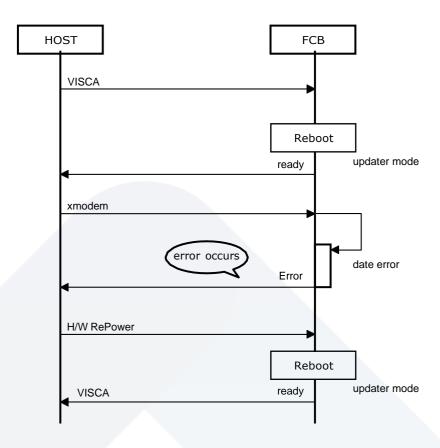
The update (UART) error patterns are as follows.





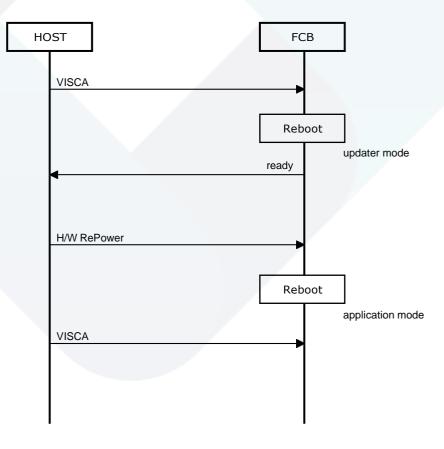
UART update-error 2





UART update-error 3

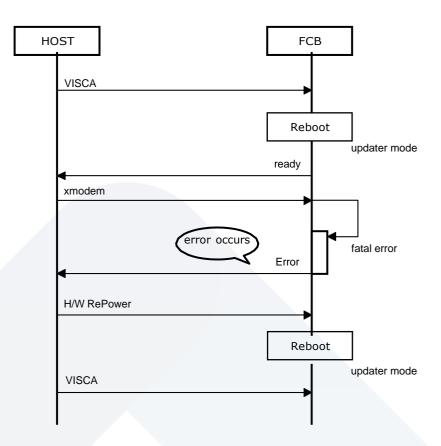
No update





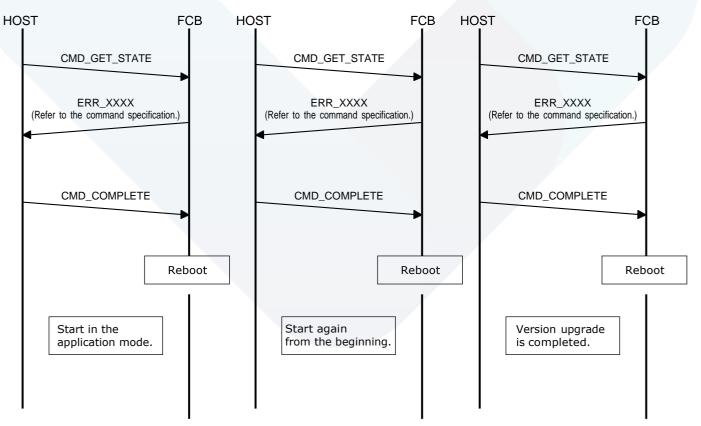
UART update-error 4





Update Procedure (USB)

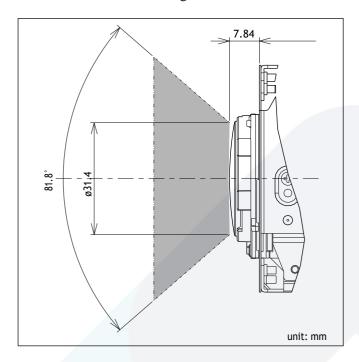
The update (USB) error patterns are as follows.



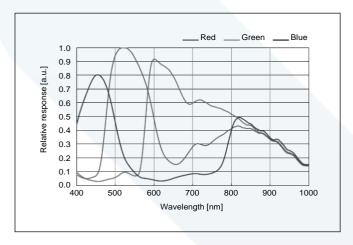


Eclipse

When designing the housing, refer to the dimensional allowance as shown in the figure below.



Spectral Sensitivity Characteristics



Use the graph as a reference value. (We can not guarantee these values.)

This data is measured when the IR cut filter is removed and the characteristics of the lens and optical source characteristics are ignored.



Initial Settings, Custom Preset and Backup

Initial Settings for the various functions of the FCB camera are indicated in the "Initial Settings" column. The "Custom Preset" column indicates whether the custom preset function can be used to store the settings. The function enables the stored settings to be recalled automatically when the camera is turned on. The "Back up at standby" column indicates whether the data is preserved even when the camera is in the standby mode.

Mode/Position setting	Initial Settings	Custom Preset	Back up at standby
Zoom Position	wide end	Ξÿ	≕
D-Zoom On/Off	Off	Ξš	=ÿ
D-Zoom Separate/Combine	Combine	≡\$	Ξÿ
D-Zoom Position	00h	Ξ*,	Ξÿ
Focus Position	_	Ξž	≡
Focus Auto/Manual	Auto	≝	≡¥
Near Limit Setting	B000 (35 cm)	=	≡ÿ
AF Sensitivity	Normal	=₹	= = = = = = = = = = = = = = = = = = =
AF Mode	Normal	==	= = = = = = = = = = = = = = = = = = =
AF Run Time	5 sec	=₹	=₹
AF Interval	5 sec	=₹	≕
WB Mode	Auto	=₹	=-
WB Data (Rgain, Bgain)	_	=₹	=₹
One Push WB Data		=ÿ	=ÿ
AE Mode	Full Auto	=>	=>
AE Response	01h	=>	≡ÿ
Shutter Position	OIII	=\$	≡ਝ ≡ਝ
Maximum Shutter Limit	1Dh: 1/2000 (59.94 fps)		
Waximum Shutter Limit	1Dh: 1/1750 (50 fps)	≡∜	≡ਝ
	1Dh: 1/2000 (29.97 fps)		
	1Dh: 1/1750 (25 fps)		
	1Eh: 1/1200 (23.98 fps)		
Minimum Shutter Limit	12h: 1/60 (59.94 fps)	Ξš	≣∜
	12h: 1/50 (50 fps)		
	10h: 1/30 (29.97 fps)		
	10h: 1/25 (25 fps)		
	12h: 1/48 (23.98 fps)		
Slow Shutter Limit	0Dh: 1/10 (59.94 fps)	≡¥	≝
	0Dh: 1/10 (29.97 fps)		
	0Dh: 1/12(50 fps)		
	0Dh: 1/12(25 fps) 0Dh: 1/12 (23.98 fps)		
Iris Position	19h: F2.0	≡ÿ	≡¥
Gain Position	01h: 0dB	≕	≡
Bright Position	_	=>	≡
Exposure Compensation On/Off	Off	≕	≡
Exposure Compensation Amount	±0	≕	≡⋾
BackLight On/Off	Off	=*	≡

A circle "\(\frac{1}{2}\)" in this column signifies that the data is preserved. A cross "\(\cdot\)" signifies that the data IS NOT preserved.



Mode/Position setting	Initial Settings	Custom	Back up
	_	Preset	at standby
Spot AE On/Off	Off	Ξ∜	Ξ₹
Spot AE Position Setting	X=8, Y=8	Ξἔ	Ξξ
Detail Level	07h	≕	≡ÿ
High Resolution Mode On/Off	Off	≕	Ξξ
LR Reverse On/Off	Off	=ÿ	ΞΫ
Freeze On/Off	Off	•	
Picture Effect	Off	=ÿ	ΞΫ
ICR On/Off	Off	=ÿ	ΞΫ
Auto ICR On/Off	Off	=ÿ	ΞΫ
Auto ICR Threshold Level	0Eh	Ξἔ	Ξÿ
Camera Memory	Same as the factory value setting		Ξ¥
Display On/Off	Off	=ÿ	ΞΫ
Mute On/Off	Off	•	
Auto ICR Alarm On/Off	Off	Ξἔ	Ξἔ
NR Level	3	=ÿ	Ξÿ
Image Stabilizer	Off	Ξἔ	Ξš
Gain Limit	Off	Ξἔ	Ξÿ
Low-Illumination Chroma Suppress	1h (Low)	=ÿ	Ξÿ
Color Gain	4h (100%)	=ÿ	Ξÿ
Color Hue	7h (0 degrees)	Ξ*,	Ξÿ
Title Display On/Off	Off	Ξἔ	ΞΫ
Title Setting	-	=ÿ	≡ÿ
Mask Setting	_	≡ÿ	Ξ¥
Mask Color Setting	-	=ÿ	Ξÿ
Center Line Display On/Off	Off	=ÿ	ΞΫ
E-Flip On/Off	Off	Ξἔ	Ξÿ
Privacy Zone On/Off	Off	Ξΰ	≡¥
Privacy Zone Setting	_	≡	Ξ¥
Camera ID	0000h		Ξ¥
ZoomPos Continuous Output On/Off	Off		Ξš
ZoomPos Continuous Output Interval	3Ch		Ξš
HLC Level	Off	Ξἔ	Ξš
HLC Mask Level	Off	======================================	≡ÿ

A circle "\(\frac{1}{2}\)' in this column signifies that the data is preserved. A cross "\(\cdot\)" signifies that the data IS NOT preserved.

Notes

- $\bullet\,$ The number of times written to Non-volatile memory (when Custom Preset is executed) is limited.
- Privacy Zone Setting while digital zooming is not preserved by Custom Preset.



Mode Condition

Condition

Mode	Power Off	Initializing	Power On	Freeze On	MemRecall
Address Set	0	0	0	0	0
IF_Clear	0	0	0	0	0
Command Cancel	0	0	0	0	0
Power On/Off	0	0	0	0	0

Lens

Mode	Power Off	Initializing	Power On	Freeze On	MemRecall	Zoom Direct	Focus Direct	ZmFo Direct	Focus Auto
Zoom Tele/Wide/Stop	×	×	0	0	×	×	0	×	0
Zoom Direct	×	×	0	0	×	0	0	×	0
Zoom Focus Direct	×	×	0	0	×	×	×	0	×
D-Zoom On/Off	×	×	0	0	×	×	0	×	0
D-Zoom Separate/Combine	×	×	0	0	×	×	0	×	0
D-Zoom Tele/Wide/Stop	×	×	0	0	×	0	0	0	0
D-Zoom ×1/Max	×	×	0	0	×	0	0	0	0
D-Zoom Direct	×	×	0	0	×	0	0	0	0
Focus Far/Near/Stop	×	×	0	0	×	0	×	×	×
Focus Direct	×	×	0	0	×	0	0	×	×
Focus Auto/Manual	×	×	0	0	×	0	×	×	0
One Push AF	×	×	0	0	×	0	×	×	×
Focus Near Limit	×	×	0	0	×	0	×	×	0
AF Sensitivity Normal/Low	×	×	0	0	×	0	0	0	0
AF Mode Norm/Interval/Zoom	×	×	0	0	×	0	0	0	0
AF Activation Time/Interval Setting	×	×	0	0	×	0	0	0	0
Camera Memory Set/Reset	×	×	0	0	×	×	×	×	0
Camera Memory Recall	×	×	0	0	0	×	×	×	0
Lens Initialize	×	X	0	0	X	×	×	×	0



White Balance

Mode	Power Off	Initializing	Power On	Freeze On	MemRecall	WB Auto	Indoor	Outdoor	Outdoor Auto	Sodium Lamp	Sodium Lamp Auto	Sodium Lamp Outdoor Auto	OnePush	ATW	Manual
WB Mode Switchover	X	×	0	0	×	0	0	0	0	0	0	0	0	0	0
One Push WB	×	×	0	0	×	×	X	×	×	×	×	×	0	×	X
RGain Setting	×	×	0	0	×	×	×	×	×	×	×	×	×	×	0
BGain Setting	×	×	0	0	×	×	×	×	×	×	×	×	×	×	0

Exposure

Mode	Power Off	Initializing	Power On	Freeze On	MemRecall	AE Full Auto	AE Manual	Shutter Priority	Iris Priority	Bright
AE Full Auto	X	X	0	0	X	0	0	0	0	0
AE Manual	X	X	0	0	×	0	0	0	0	0
Shutter Priority	×	×	0	0	×	0	0	0	0	0
Iris Priority	×	×	0	0	×	0	0	0	0	0
Bright	X	×	0	0	×	×	X	0	×	0
Shutter Setting	×	×	0	0	×	×	0	0	×	×
Iris Setting	×	×	0	0	×	×	0	×	0	×
Gain Setting	×	X	0	0	X	X	0	×	×	×
Bright Setting	X	X	0	0	×	×	X	×	×	0
Auto Slow Shutter On/Off	X	X	0	0	×	0	0	0	0	0
Exposure Compensation On/Off	X	X	0	0	×	0	0	0	0	0
Exposure Compensation Setting	×	×	0	0	×	0	0	0	0	0
BackLight On/Off	×	X	0	0	×	0	0	0	0	0
SpotAE On/Off	×	X	0	0	×	0	0	0	0	0
SpotAE Setting	×	×	0	0	X	0	0	0	0	0
Defog On/Off	×	×	0	0	0	0	0	0	0	0
Minimum Shutter On/Off	×	X	0	0	X	0	0	0	0	0
VE On/Off	×	×	0	0	X	0	0	0	0	0
HLC Setting (On/Off/Mask Level)	×	X	0	0	X	0	0	0	0	0



Others

Mode	Power Off	Initializing	Power On	Freeze On	MemRecall
Aperture Setting	X	X	0	0	X
High Resolution Mode On/Off	×	×	0	0	0
LR_Reverse On/Off	×	×	0	0	0
Freeze On/Off	×	×	0	0	0
Picture Effect Setting	×	×	0	0	0
ICR On/Off	×	×	0	0	0
Auto ICR On/Off	X	X	0	0	X
Auto ICR Threshold Level Setting	×	×	0	0	0
Auto ICR Alarm On/Off	×	0	0	0	0
Display On/Off	×	×	0	0	0
Mute On/Off	×	×	0	0	0
Title Setting	×	×	0	0	0
Mask On/Off	×	×	0	0	0
Mask Setting	×	×	0	0	0
MD On/Off	×	×	0	0	0
ID Write	×	×	0	0	0
Memory Save	×	×	0	0	0
Register Value Setting	X	X	0	0	0
NR Level Setting	X	X	0	0	0
Chroma Suppress	×	X	0	0	0
Color Gain	×	X	0	0	0
Color Hue	×	×	0	0	0



Command List

VISCA/RS-232C Commands

This Manual outlines an RS-232C control protocol and command list for certain Sony cameras from which control software can be developed.

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Overview of VISCA

In VISCA, the device outputting commands, for example, a computer, is called the controller. The device receiving the commands, an FCB camera is called the peripheral device. In VISCA, up to seven peripheral devices like the FCB camera can be connected to one controller using communication conforming to the RS-232C standard. The parameters of RS-232C are as follows.

- Communication speed: 9.6 kbps/19.2 kbps/38.4 kbps/115.2 kbps
- Data bits : 8
- Start bit: 1Stop bit: 1
- Non parity

Flow control using XON/XOFF and RTS/CTS, etc., is not supported.



VISCA Communication Specifications

VISCA packet structure

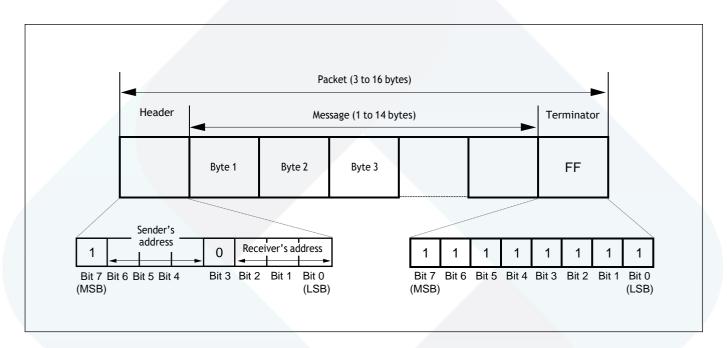
The basic unit of VISCA communication is called a packet. The first byte of the packet is called the header and comprises the sender's and receiver's addresses. For example, the header of the packet sent to the FCB camera assigned address 1 from the controller (address 0) is hexadecimal 81h. The packet sent to the camera assigned address 2 is 82h. In the command list, as the header is 8X, input the address of the camera at X. The header of the reply packet from the camera assigned address 1 is 90h. The packet from the camera assigned address 2 is A0h.

Transmitting the commands regardless of the camera ID is called broadcasting.

In the case of broadcast, the header should be hexadecimal 88h.

When the terminator is FFh, it signifies the end of the packet.

The camera supports only Address Set and IF_Clear among the commands transmitted by broadcasting.



Command and inquiry

Command

Sends operational commands to the FCB camera.

Inquiry

Used for inquiring about the current state of the FCB camera.

Command Packet Note

Inquiry 8X QQ RR ... FF $QQ^{(1)} = Command/Inquiry,$

RR²⁾ = category code

1) QQ = 01 (Command), 09 (Inquiry)

2) RR = 00 (Interface), 04 (camera 1), 06 (Pan/Tilt), 07 (camera 2)

X = 1 to 7: FCB camera address



Responses for commands and inquiries

Acknowledge message

Returned by the FCB camera when it receives a command. No Acknowledge message is returned for inquiries.

Completion message

Returned by the FCB camera when execution of commands or inquiries is completed. In the case of inquiry commands, it will contain reply data for the inquiry after the 3rd byte of the packet. If the Acknowledge message is omitted, the socket number will contain 0.

Reply Packete

Acknowledge X0 4Y FF
Completion (Commands) X0 5Y FF
Completion (Inquiries) X0 5Y ... FF

X = 9 to F: FCB camera address + 8, Y = socket number

Error message

When a command could not be executed or failed, an error message is returned instead of the Acknowledge message. After an Acknowledge message, an error message may be returned if the process of some command (zoom, etc.) has not been completed.

When a inquiry command could not be executed or failed, an error message is returned instead of the completion message.

Error Packet	Description				
X0 6Y 01 FF	Message length error (>14 bytes)				
X0 6Y 02 FF	Syntax Error				
X0 6Y 03 FF	Command buffer full				
X0 6Y 04 FF	Command cancelled				
X0 6Y 05 FF	No socket (to be cancelled)				
X0 6Y 41 FF	Command not executable				
X = 9 to F: FCB camera address + 8. Y = socket number					

Socket number

When command messages are sent to the FCB camera, send the next command message after waiting for the completion message or error message to return. However to deal with advanced uses, the FCB camera has two buffers (memories) for commands, so that up to two commands including the commands currently being executed can be received. When the FCB camera receives commands, it notifies the sender which command buffer was used using the socket number of the Acknowledge message. As the completion message or error message also has a socket number, it indicates which command has ended. Even when two command buffers are being used at any one time, an FCB camera management command and some inquiry messages can be executed.

The Acknowledge message is not returned for these commands and inquiries, and only the completion message of socket number 0 is returned.

Command execution cancel

To cancel a command which has already been sent, send the Cancel command as the next command. To cancel one of any two commands which have been sent, use the cancel message.

Cancel Packet

Cancel 8X 2Y FF

X = 1 to 7: FCB camera address, Y = socket number

An error message will be returned for this command, but this is not a fault. It indicates that the command has been canceled.



VISCA Command/Acknowledge Protocol

81 01 04 38 02 FF		
(Example)	90 41 FF (Acknowledge) +90 51 FF (Completion) 90 42 FF 90 52 FF	Returns Acknowledge when a command has been accepted, and Completion when a command has been executed.
81 01 04 38 FF (Example)	90 60 02 FF (Syntax Error)	Accepted a command which is not supported or a command lacking parameters.
81 01 04 38 02 FF (Example)	90 60 03 FF (Command Buffer Full)	There are two commands currently being executed, and the command could not be accepted.
81 01 04 08 02 FF (Example)	90 61 41 FF (Command Not Executable) 90 62 41 FF	Could not execute the command in the current mode.
81 09 04 38 FF (Example)	90 50 <u>02</u> FF (Completion)	Acknowledge is not returned for the inquiry command.
81 09 05 38 FF (Example)	90 60 02 FF (Syntax Error)	Accepted an incompatible command.
88 30 <u>01</u> FF	88 30 <u>02</u> FF	Returned the device address to +1.
88 01 00 01 FF	88 01 00 01 FF	Returned the same command.
8x 01 00 01 FF	z0 50 FF (Completion)	Acknowledge is not returned for this command.
8x 2y FF	z0 6y 04 FF (Command Canceled) z0 6y 05 FF (No Socket)	Returned when the command of the socket specified is canceled. Completion for the command canceled is not returned. Returned when the command of the specified socket has already
	81 01 04 38 FF (Example) 81 01 04 38 02 FF (Example) 81 01 04 08 02 FF (Example) 81 09 04 38 FF (Example) 81 09 05 38 FF (Example) 88 30 01 FF 88 01 00 01 FF 8x 01 00 01 FF	90 42 FF 90 52 FF 81 01 04 38 FF (Example) 81 01 04 38 02 FF (Example) 81 01 04 08 02 FF (Command Buffer Full) 81 01 04 08 02 FF (Example) 90 61 41 FF (Command Not Executable) 90 62 41 FF 81 09 04 38 FF (Example) 81 09 05 38 FF (Example) 81 09 05 38 FF (Example) 88 30 01 FF 88 30 02 FF 88 01 00 01 FF 88 01 00 01 FF 8x 01 00 01 FF 20 6y 04 FF (Command Canceled)



VISCA Camera-Issued Messages

Acknowledge/Completion Messages

	Command Messages	Comments
Acknowledge	z0 4y FF	Returned when the command is accepted.
	(y:Socket No.)	
Completion	z0 5y FF	Returned when the command has been executed.
	(y:Socket No.)	

z = Device address + 8

Error Messages

	Command Messages	Comments
Syntax Error	z0 60 02 FF	Returned when the command format is different or when a command with illegal
		command parameters is accepted.
Command Buffer Full	z0 60 03 FF	Indicates that two sockets are already being used (executing two commands) and the
		command could not be accepted when received.
Command Canceled	z0 6y 04 FF	Returned when a command which is being executed in a socket specified by the cancel
	(y:Socket No.)	command is canceled. The completion message for the command is not returned.
No Socket	z0 6y 05 FF	Returned when no command is executed in a socket specified by the cancel command,
	(y:Socket No.)	or when an invalid socket number is specified.
Command Not Executable	z0 6y 41 FF	Returned when a command cannot be executed due to current conditions. For example,
	(y:Socket No.)	when commands controlling the focus manually are received during auto focus.

Network Change Message

	Command Message	Comments
Network Change	z0 38 FF	Issued when power is being routed.



FCB Camera Commands

Command List (1/7)

Command Set	Command	Command Packet	Comments
AddressSet	Broadcast	88 30 0p FF	Address Setting p:Address
IF_Clear	_	8x 01 00 01 FF	I/F Clear
	Broadcast	88 01 00 01 FF	
CommandCancel	_	8x 2p FF	p: Socket No. (=1 or 2)
CAM_Power	On	8x 01 04 00 02 FF	Power On/Off
	Off (Standby)	8x 01 04 00 03 FF	
CAM_Zoom	Stop	8x 01 04 07 00 FF	-
	Tele (Standard)	8x 01 04 07 02 FF	
	Wide (Standard)	8x 01 04 07 03 FF	
	Tele (Variable)	8x 01 04 07 2p FF	p=0 (Low) to 7 (High)
	Wide (Variable)	8x 01 04 07 3p FF	
	Direct	8x 01 04 47 0p 0q 0r 0s FF	pqrs: Zoom Position
			Min. 0000h
			Max. 4000h (In Separate mode)
			Max. 4000h (In Combine mode and DZoom=Off)
			Max. 5556h (In Combine mode, DZoom=Super Resolution Zoom, and monitoring mode QFHD)
			Max. 6000h (In Combine mode, DZoom=Super Resolution
			Zoom, and monitoring mode FHD or less)
			Max. 7AC0h (In Combine mode and DZoom=On)
CAM_DZoom	On	8x 01 04 06 02 FF	Digital Zoom On/Off/Super Resolution Zoom
	Off	8x 01 04 06 03 FF	
	Super Resolution Zoom	8x 01 04 06 04 FF	
	Combine Mode	8x 01 04 36 00 FF	Optical/Digital Zoom Combined
	Separate Mode	8x 01 04 36 01 FF	Optical/Digital Zoom Separate
	Stop	8x 01 04 06 00 FF	-
	Tele (Variable)	8x 01 04 06 2p FF	p=0 (Low) to 7 (High)
	Wide (Variable)	8x 01 04 06 3p FF	* Enabled during Separate Mode
	x1/Max	8x 01 04 06 10 FF	x1/MAX Magnification Switchover
			* Enabled during Separate Mode
	Direct	8x 01 04 46 00 00 0p 0q FF	pq: D-Zoom Position (00h to EBh)
			* Enabled during Separate Mode
CAM_Focus Mode	Auto Focus	8x 01 04 38 02 FF	AF On/Off
	Manual Focus	8x 01 04 38 03 FF	
	Auto/Manual	8x 01 04 38 10 FF	
CAM_Focus	Stop	8x 01 04 08 00 FF	_
	Far (Standard)	8x 01 04 08 02 FF	
	Near (Standard)	8x 01 04 08 03 FF	
	Far (Variable)	8x 01 04 08 2p FF	p=0 (Low) to 7 (High)
	Near (Variable)	8x 01 04 08 3p FF	
	Direct	8x 01 04 48 0p 0q 0r 0s FF	pqrs: Focus Position 0000h to F000h
	One Push Trigger	8x 01 04 18 01 FF	One Push AF Trigger
	Near Limit	8x 01 04 28 0p 0q 0r 0s FF	pqrs: Focus Near Limit Position 1000h to F000h
CAM_AFMode	Normal AF	8x 01 04 57 00 FF	AF Movement Mode
	Interval AF	8x 01 04 57 01 FF	
	Zoom Trigger AF	8x 01 04 57 02 FF	
	Active/Interval Time	8x 01 04 27 0p 0q 0r 0s FF	pq: Movement Time, rs: Interval



Command List (2/7)

Command Set	Command	Command Packet	Comments
CAM_SpotFocus	On	8x 01 05 08 02 FF	pq: X (0h to Fh), rs: Y (0h to Fh)
	Off	8x 01 05 08 03 FF	
	Position	8x 01 05 68 0p 0q 0r 0s FF	
CAM_AFSensitivity	Normal	8x 01 04 58 02 FF	AF Sensitivity switching
	Low	8x 01 04 58 03 FF	
CAM_IRCorrection	Standard	8x 01 04 11 00 FF	Focus IR compensation data switching
	IR Light	8x 01 04 11 01 FF	
CAM_ZoomFocus	Direct	8x 01 04 47 0p 0q 0r 0s	pqrs: Zoom Position
CAM I 'Z' I'	Y	0t 0u 0v 0w FF	tuvw: Focus Position
CAM_Initialize	Lens	8x 01 04 19 01 FF	Lens Initialization Start
CAM HID	Camera	8x 01 04 19 03 FF	Camera reset
CAM_WB	Auto	8x 01 04 35 00 FF	Normal Auto
	Indoor	8x 01 04 35 01 FF	Indoor mode
	Outdoor	8x 01 04 35 02 FF	Outdoor mode
	One Push WB	8x 01 04 35 03 FF	One Push WB mode
	ATW	8x 01 04 35 04 FF	Auto Tracing White Balance
	Manual	8x 01 04 35 05 FF	Manual Control mode
	Outdoor Auto	8x 01 04 35 06 FF	Outdoor auto
	Sodium Lamp Auto	8x 01 04 35 07 FF	Auto including sodium lamp source
	Sodium Lamp	8x 01 04 35 08 FF	Sodium lamp source fixed mode
	Sodium Lamp Outdoor Auto	8x 01 04 35 09 FF	Outdoor auto including sodium lamp source
CAM_WBTrigger	One Push Trigger	8x 01 04 10 05 FF	One Push WB Trigger
CAM_RGain	Reset	8x 01 04 03 00 FF	Manual Control of R Gain
	Up	8x 01 04 03 02 FF	
	Down	8x 01 04 03 03 FF	
	Direct	8x 01 04 43 00 00 0p 0q FF	pq: R Gain 00h to FFh
CAM_BGain	Reset	8x 01 04 04 00 FF	Manual Control of B Gain
	Up	8x 01 04 04 02 FF	
	Down	8x 01 04 04 03 FF	
	Direct	8x 01 04 44 00 00 0p 0q FF	pq: B Gain 00h to FFh
CAM_AE	Full Auto	8x 01 04 39 00 FF	Full Auto
	Manual	8x 01 04 39 03 FF	Manual Control mode
	Shutter Priority	8x 01 04 39 0A FF	Shutter Priority Auto Exposure mode
	Iris Priority	8x 01 04 39 0B FF	Iris Priority Auto Exposure mode
	Gain Priority	8x 01 04 39 0E FF	Gain Priority Auto Exposure mode
	Bright	8x 01 04 39 0D FF	Bright Mode (Manual control)
CAM_	On	8x 01 05 39 02 FF	p: Position
LowLightBasisBrightness	Off	8x 01 05 39 03 FF	
	Position	8x 01 05 49 0p FF	
CAM_Shutter	Reset	8x 01 04 0A 00 FF	Shutter Setting
	Up	8x 01 04 0A 02 FF	
	Down	8x 01 04 0A 03 FF	
	Direct	8x 01 04 4A 00 00 0p 0q FF	pq: Shutter Position
CAM_MaxShutter	Limit	8x 01 05 2A 00 0p 0q FF	pq: High-speed shutter limit
CAM_MinShutter	Limit	8x 01 05 2A 01 0p 0q FF	pq: Low-speed shutter limit



Command List (3/7)

Command Set	Command	Command Packet	Comments
CAM_SlowShutter	On	8x 01 04 5A 02 FF	Slow Shutter On/Off
	Off	8x 01 04 5A 03 FF	
	Limit	8x 01 05 5A 0p 0q FF	pq: Slow Shutter Limit
CAM_Iris	Reset	8x 01 04 0B 00 FF	Iris Setting
	Up	8x 01 04 0B 02 FF	
	Down	8x 01 04 0B 03 FF	
	Direct	8x 01 04 4B 00 00 0p 0q FF	pq: Iris Position
CAM_Gain	Reset	8x 01 04 0C 00 FF	Gain Setting
	Up	8x 01 04 0C 02 FF	
	Down	8x 01 04 0C 03 FF	
	Direct	8x 01 04 4C 00 00 0p 0q FF	pq: Gain Position
	Gain Limit	8x 01 04 2C 0p FF	p: Gain Limit
	Gain Point Pos	8x 01 05 4C 0p 0q FF	pq: Gain Point
	Gain Point On/Off	8x 01 05 0C 0p FF	p:2=On, 3=Off
CAM_Bright	Reset	8x 01 04 0D 00 FF	Bright Setting
	Up	8x 01 04 0D 02 FF	
	Down	8x 01 04 0D 03 FF	
	Direct	8x 01 04 4D 00 00 0p 0q FF	pq: Bright Position
CAM_ExpComp	On	8x 01 04 3E 02 FF	Exposure Compensation On/Off
	Off	8x 01 04 3E 03 FF	
	Reset	8x 01 04 0E 00 FF	Exposure Compensation Amount Setting
	Up	8x 01 04 0E 02 FF	
	Down	8x 01 04 0E 03 FF	
	Direct	8x 01 04 4E 00 00 0p 0q FF	pq: ExpComp Position 00h to 0Eh
CAM_Backlight	On	8x 01 04 33 02 FF	Back Light Compensation On/Off
	Off	8x 01 04 33 03 FF	
CAM_SpotAE	On	8x 01 04 59 02 FF	Spot Auto Exposure Setting
	Off	8x 01 04 59 03 FF	
	Position	8x 01 04 29 0p 0q 0r 0s FF	pq: X (0h to Fh), rs: Y (0h to Fh)
CAM_AE_Response	Direct	8x 01 04 5D pp FF	pp: Auto Exposure Response Setting (01h to 30h), default value: 01h
CAM_VE	Off	8x 01 04 3D 03 FF	VE Off
	VE On	8x 01 04 3D 06 FF	VE On
	Set Parameter	8x 01 04 2D 00 0q 0r 0s 00 00 00 00 FF	q: Display brightness level (0: Dark to 6: Bright) r: Brightness compensation selection (0: Very dark, 1: Dark, 2: Standard, 3: Bright) s: Compensation level (0: Low, 1: Mid, 2: High)
CAM_Defog	On	8x 01 04 37 02 0p FF	Defog On/Off
	Off	8x 01 04 37 03 00 FF	p: Defog level (0: mid, 1: low, 2: mid, 3: high)



Command List (4/7)

Command Set	Command	Command Packet	Comments	
CAM_Aperture	Reset	8x 01 04 02 00 FF	Aperture Control	
	Up	8x 01 04 02 02 FF		
	Down	8x 01 04 02 03 FF		
	Level	8x 01 04 42 00 00 0p 0q FF	pq: Aperture Gain (00h to 0Fh)	
	Mode	8x 01 05 42 01 0p FF	p: Auto (0)/Manual (1) selection	
	BandWidth	8x 01 05 42 02 0p FF	p: Bandwidth setting 0: default (initial value) 1: low bandwidth 2: mid bandwidth 3: wide bandwidth 4: broad bandwidth	
	Crispening	8x 01 05 42 03 0p FF	p: Crispening (0h to 7h)	
	H/V balance	8x 01 05 42 04 0p FF	p: H/V Balance (5h to 9h)	
	B/W balance	8x 01 05 42 05 0p FF	p: B/W Balance (0h to 4h)	
	Limit	8x 01 05 42 06 0p FF	p: Limit (0h to 7h)	
	HighLightDetail	8x 01 05 42 07 0p FF	p: High light detail (0h to 4h)	
	SuperLow	8x 01 05 42 08 0p FF	p: Super low emphasis (0h to 7h)	
CAM_HR	On	8x 01 04 52 02 FF	High Resolusion Mode On/Off	
	Off	8x 01 04 52 03 FF		
CAM_NR	Noise Reduction	8x 01 04 53 pp FF	p: NR setting (00h: Off, 01h to 05h: level, 7Fh: 2D/3D manual setting)	
	2D NR/3D NR	8x 01 05 53 0p 0q FF	p: 2D NR level (0h to 5h), q: 3D NR level (0h to 5h)	
CAM_Stabilizer	On	8x 01 04 34 02 FF	Image Stabilizer On/Off	
	Off	8x 01 04 34 03 FF		
CAM_Gamma	_	8x 01 04 5B 0p FF	p: Gamma Setting (0: Standard, 1: Straight, 2: Pattern)	
	Pattern	8x 01 05 5B 0p 0q 0r FF	pqr: Selection pattern (001h to 200h)	
	Offset	8x 01 04 1E 00 00 00 0s 0t 0u FF	s: Polarity offset (0 is plus, 1 is minus) tu: Offset s=0 (00h to 40h) Offset s=1 (00h to 40h)	
CAM_HighSensitivity	On	8x 01 04 5E 02 FF	High Sensitivity mode On/Off	
	Off	8x 01 04 5E 03 FF		
CAM_LR_Reverse	On	8x 01 04 61 02 FF	LR Reverse On/Off	
	Off	8x 01 04 61 03 FF		
CAM_Freeze	On	8x 01 04 62 02 FF	Freeze On/Off	
	Off	8x 01 04 62 03 FF		
CAM_PictureEffect	Off	8x 01 04 63 00 FF	Picture Effect Setting	
	Black & White	8x 01 04 63 04 FF		
CAM_PictureFlip	On	8x 01 04 66 02 FF	E-Flip On/Off	
	Off	8x 01 04 66 03 FF		
CAM_ICR	On	8x 01 04 01 02 FF	ICR Mode On/Off	
	Off	8x 01 04 01 03 FF		
CAM_AutoICR	On	8x 01 04 51 02 FF	Auto ICR Mode On/Off	
	Off	8x 01 04 51 03 FF		
	Threshold	8x 01 04 21 00 00 0p 0q FF	pq: ICR On 3 Off Threshold Level (00h to FFh)	
CAM	On	8x 01 04 31 02 FF	Auto ICR switching Alarm On/Off	
_AutoICRAlarmReply	Off	8x 01 04 31 03 FF		
	(Reply)	y0 07 04 31 02 FF	ICR Off □ On	
			ICR Off □ On ICR On □ Off	



Command List (5/7)

Command Set	Command	Command Packet	Comments				
CAM_Memory	Reset	8x 01 04 3F 00 pp FF	pp: Memory Number (=0h to 63h)				
	Set	8x 01 04 3F 01 pp FF					
	Recall	8x 01 04 3F 02 pp FF					
CAM_Custom	Reset	8x 01 04 3F 00 7F FF	Starts up in this mode when the power is turned on.				
	Set	8x 01 04 3F 01 7F FF					
	Recall	8x 01 04 3F 02 7F FF	-				
CAM_MemSave			X: 00h to 07h (Address), total 16 byte				
6.1 <u>_</u>		on or or 20 our op oq or our	pqrs: 0000h to FFFFh (Data)				
CAM_Display	On	8x 01 04 15 02 FF	Display On/Off				
	Off	8x 01 04 15 03 FF					
	On/Off	8x 01 04 15 10 FF					
CAM_MultiLineTitle	Title Set1	8x 01 04 73 1L 00 nn pp qq 00 00 00 00 00 00 FF	L: Line Number, nn: H-position pp: Color, qq: Blink				
	Title Set2	8x 01 04 73 2L mm nn pp qq rr ss tt uu vv ww FF	L: Line Number, mnpqrstuvw: Setting of characters (1 to 10)				
	Title Set3	8x 01 04 73 3L mm nn pp	L: Line Number,				
	Title Clear	qq rr ss tt uu vv ww FF 8x 01 04 74 1p FF	mnpqrstuvw: Setting of characters (11 to 20) Title Setting clear (p: 0h to Ah, F= all lines)				
	On	8x 01 04 74 2p FF	Title display On/Off (p: 0h to Ah, F= all lines)				
	Off	8x 01 04 74 2p FF	Title display On On (p. on to An, 1 – an inies)				
CAM More		•	Martin - On /Off				
CAM_Mute	On	8x 01 04 75 02 FF	Muting On/Off				
	Off	8x 01 04 75 03 FF					
	On/Off	8x 01 04 75 10 FF					
CAM_PrivacyZone	SetMask	8x 01 04 76 mm nn 0r 0r 0s 0s FF	mm: Mask Settings nn 00: Modify, 01: New				
		OF OF OS OS FF	rr: W, ss: H				
	SetMaskTable	8x 01 05 70 0p FF p: Table (0h to 1h)					
	Display	8x 01 04 77 pp pp pp pFF	Mask Display On/Off				
			pp pp pp pp: Mask Settings (0: Off, 1: On)				
	SetMaskColor	8x 01 04 78 pp pp pp pp	pp pp pp pp: Mask Color Settings				
		qq rr FF	qq: Color Setting when 0 is selected rr: Color Setting when 1 is selected				
	SetPanTiltAngle	8x 01 04 79 0p 0p 0p	Pan/Tilt Angle Settings				
		0q 0q 0q FF	ppp: Pan				
	C DESTRICT	0.01047B	qqq: Tilt				
	SetPTZMask	8x 01 04 7B mm 0p 0p 0p 0q 0q 0q 0r 0r 0r 0r FF	Pan/Tilt/Zoom Settings for Mask ppp: Pan, qqq: Tilt, rrrr: Zoom, mm: Mask Settings				
	Non InterlockMask	8x 01 04 6F mm	mm: Non_Interlock Mask Settings				
		Op Op Oq Oq Or Or Os Os FF	pp: X, qq: Y, rr: W, ss: H				
	CenterLineOff	8x 01 04 7C 03 FF	Center Line Display Off				
	CenterLineOn	8x 01 04 7C 04 FF	Center Line Display On				
CAM_IDWrite	_	8x 01 04 22 0p 0q 0r 0s FF	pqrs: Camera ID (=0000h to FFFFh)				
CAM_Continuous	On	8x 01 04 69 02 FF	Zoom Position data Continuous Output On/Off				
ZoomPosReply	Off	8x 01 04 69 03 FF					
	(Reply)	y0 07 04 69 0p 0p 0q 0q 0q 0q FF	pp: D-Zoom Position				
			* 00: When Zoom Mode is Combine				
			qqqq: Zoom Position				
CAM_ZoomPos ReplyIntervalTimeSet	_	8x 01 04 6A 00 00 0p 0p FF	pp: Interval Time [V cycle] 01h to FFh				
CAM_Continuous	On	8x 01 04 16 02 FF	Focus Position data Continuous Output On/Off				
FocusPosReply	Off	8x 01 04 16 03 FF					
	(Reply)	y0 07 04 16 00 00 0p 0p 0p 0p FF	pppp: Focus Position				



Command List (6/7)

Command Set	Command	Command Packet	Comments
CAM_FocusPosReply	_	8x 01 04 1A 00 00 0p 0p FF	pp: Interval Time [V cycle] 01h to FFh
IntervalTimeSet			
CAM_RegisterValue — 8x 01 04 24 mn 0p 0q FF		8x 01 04 24 mn 0p 0q FF	mn: Register No. (=00h to 7Fh)
<u> </u>			pq: Register Value (=00h to FFh)
CAM_ChromaSuppress	_	8x 01 04 5F 0p FF	p: Chroma Suppress setting level
İ			00: Off
l			01h to 03h: On (3 levels).
			Effect increases as the level number increases.
CAM_ColorGain	Direct	8x 01 04 49 00 00 00 0p FF	p: Color Gain Setting 0h (60%) to Eh (200%)
CAM_ColorHue	Direct	8x 01 04 4F 00 00 00 0p FF	p: Color Hue Setting 0h (-14 degrees) to Eh (+14 degrees)
CAM_ExExpComp	Reset	8x 01 04 1F 0E 00 00 FF	Exposure compensation reset
(Extended command)	Up	8x 01 04 1F 0E 02 pp FF	Exposure compensation up pp: Step number pp=00h to 7Fh (However, 00h is the same operation as 01h.)
	Down	8x 01 04 1F 0E 03 pp FF	Exposure compensation down pp: Step number pp=00h to 7Fh (However, 00h is the same operation as 01h.)
	Direct	8x 01 04 1F 4E 00 00 0p 0q FF	Set the exposure compensation to the specified level pq: Level pq=00h to FFh
CAM_ExAperture	Reset	8x 01 04 1F 02 00 00 FF	Aperture control reset
(Extended command)	Up	8x 01 04 1F 02 02 pp FF	Aperture control up pp: Step number pp=00h to 7Fh (However, 00h is the same operation as 01h.)
	Down	8x 01 04 1F 02 03 pp FF	Aperture control down pp: Step number pp=00h to 7Fh (However, 00h is the same operation as 01h.)
	Direct	8x 01 04 1F 42 00 00 0p 0q FF	Set the aperture control to the specified level pq: Level pq=00h to FFh
CAM_ExAutoICR (Extended command)	Threshold (ON→OFF)	8x 01 04 1F 21 00 00 0p 0q FF	pq: ICR ON→OFF threshold level when Auto ICR pq=00h to FFh
	On Level	8x 01 04 1F 21 01 00 0r 0s FF	pq: ICR OFF→ON threshold level when Auto ICR pq=00h to 16h
CAM_ExColorGain (Extended command)	Direct	8x 01 04 1F 49 00 00 0p 0q FF	Color Gain Setting pq: Gain setting level pq=00h (0%) to FFh (200%)
CAM_ExColorHue	Direct	8x 01 04 1F 4F 00 00 0p 0q FF	Color Hue Setting
(Extended command)			pq: Phase setting level pq=00h (-14 degrees) to FFh (14 degrees)
CAM_HLC	Parameter Set	8x 01 04 14 0p 0q FF	p: HLC level (0: Off, 1: On) q: HLC mask level (0: Off, 1: On)
CAM_ColorBar	Off	8x 01 7E 04 7D 00 FF	_
	On (Color bar 100% 8 colors)	8x 01 7E 04 7D 01 FF	
l	On (Color bar 100%	8x 01 7E 04 7D 02 FF	
l.	7 colors)		



Command List (7/7)

Command Set	Command Packet		Comments
CAM_ePT	On	8x 01 7E 06 00 02 FF	
	Off	8x 01 7E 06 00 03 FF	
	Absolute Position	8x 01 7E 06 20 00 00 0y 0y 0y 0y 0z	yyyy: Pan Position, zzzz: Tilt Position
		0z 0z 0z FF	*Supplementary explanation:
			Pan Position is specified in units of 6 pixels and Tilt
			Position is specified in units of 4.5 pixels (cut off after the
			decimal point)
CAM_MaintenanceMode	Step1	8x 01 04 00 0C FF	Used in maintenance mode
	Step2	8x 01 04 00 0D FF	
	Step3	8x 01 04 00 13 FF	
	Step4	8x 01 04 00 04 FF	
	Updata	8x 01 04 00 20 FF	



Inquiry Command List (1/4)

Inquiry Command	Command Packet	Inquiry Packet	Comments
CAM_PowerInq	8x 09 04 00 FF	y0 50 02 FF	On
		y0 50 03 FF	Off (Standby)
CAM_ZoomPosInq	8x 09 04 47 FF	y0 50 0p 0q 0r 0s FF	pqrs: Zoom Position
CAM_DZoomModeInq	8x 09 04 06 FF	y0 50 02 FF	D-Zoom On
		y0 50 03 FF	D-Zoom Off
		y0 50 04 FF	Super Resolution Zoom
CAM_DZoomC/SModeInq	8x 09 04 36 FF	y0 50 00 FF	Combine Mode
		y0 50 01 FF	Separate Mode
CAM_DZoomPosInq	8x 09 04 46 FF	y0 50 00 00 0p 0q FF	pq: D-Zoom Position
CAM_FocusModeInq	8x 09 04 38 FF	y0 50 02 FF	Auto Focus
		y0 50 03 FF	Manual Focus
CAM_FocusPosInq	8x 09 04 48 FF	y0 50 0p 0q 0r 0s FF	pqrs: Focus Position
CAM_FocusNearLimitInq	8x 09 04 28 FF	y0 50 0p 0q 0r 0s FF	pqrs: Focus Near Limit Position
CAM_SpotFocusModeInq	8x 09 05 08 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_SpotFocusPosInq	8x 09 05 68 FF	y0 50 0p 0q 0r 0s FF	pq: X, rs: Y
CAM_AFSensitivityInq	8x 09 04 58 FF	y0 50 02 FF	AF Sensitivity Normal
		y0 50 03 FF	AF Sensitivity Low
CAM_AFModeInq	8x 09 04 57 FF	y0 50 00 FF	Normal AF
Crivi_rii Wodeinq	0.000013711	y0 50 01 FF	Interval AF
		y0 50 02 FF	Zoom Trigger AF
CAM_AFTimeSettingInq	8x 09 04 27 FF	y0 50 0p 0q 0r 0s FF	pq: Movement Time, rs: Interval
CAM_LowLightBasis	8x 09 05 39 FF	y0 50 02 FF	On
BrightnessInq	8x 09 03 39 11	y0 50 02 FF	Off
CAM_LowLightBasis	8x 09 05 49 FF	y0 50 0p FF	p: Position
BrightnessPosInq	8x 09 03 49 FF	y 0 50 0p FF	p. Position
CAM_IRCorrectionInq	8x 09 04 11 FF	y0 50 00 FF	Standard
		y0 50 01 FF	IR Light
CAM_WBModeInq	8x 09 04 35 FF	y0 50 00 FF	Auto
		y0 50 01 FF	Indoor
		y0 50 02 FF	Outdoor
		y0 50 03 FF	One Push WB
		y0 50 04 FF	ATW
		y0 50 05 FF	Manual
		y0 50 06 FF	Outdoor Auto
		y0 50 07 FF	Sodium Lamp Auto
		y0 50 08 FF	Sodium Lamp
		y0 50 09 FF	Sodium Lamp Outdoor Auto
CAM_RGainInq	8x 09 04 43 FF	y0 50 00 00 0p 0q FF	pg: R Gain
CAM_BGainInq	8x 09 04 44 FF	y0 50 00 00 0p 0q FF	pq: B Gain
CAM_AEModeInq	8x 09 04 39 FF	y0 50 00 FF	Full Auto
CAN_ALWOUGHIQ	0.07043711	y0 50 03 FF	Manual
		y0 50 03 FF	Shutter Priority
		y0 50 0A FF	Iris Priority
		y0 50 0B FF y0 50 0D FF	·
CAM ShyttarDasIr -	9v 00 04 4 A EE	•	Bright Pos Shutter Position
CAM_ShutterPosInq	8x 09 04 4A FF	y0 50 00 00 0p 0q FF	pq: Shutter Position
CAM_MaxShutterInq	8x 09 05 2A 00 FF	y0 50 0p 0q FF	pq: High-speed shutter limit
CAM_MinShutterInq	8x 09 05 2A 01 FF	y0 50 0p 0q FF	pq: Low-speed shutter limit
CAM_SlowShutterInq	8x 09 04 5A FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_SlowShutterLimitInq	8x 09 05 5A FF	y0 50 0p 0q FF	pq: Slow Shutter Limit

Inquiry Command List (2/4)

Inquiry Command	Command Packet	Inquiry Packet	Comments
CAM_IrisPosInq	8x 09 04 4B FF	y0 50 00 00 0p 0q FF	pq: Iris Position
CAM_GainPosInq	8x 09 04 4C FF	y0 50 00 00 0p 0q FF	pq: Gain Position
CAM_GainLimitInq	8x 09 04 2C FF	y0 50 0q FF	p: Gain Limit
CAM_GainPointInq	8x 09 05 4C FF	y0 50 0p 0q FF	pq: Gain Point
Gain Point On/Off Inq	8x 09 05 0C FF	y0 50 02 FF	On
•		y0 50 03 FF	Off
CAM_BrightPosInq	8x 09 04 4D FF	y0 50 00 00 0p 0q FF	pq: Bright Position
CAM_ExpCompModeInq	8x 09 04 3E FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_ExpCompPosInq	8x 09 04 4E FF	y0 50 00 00 0p 0q FF	pq: ExpComp Position
CAM_BackLightModeInq	8x 09 04 33 FF	y0 50 02 FF	On
or ma_buttlegamarousinq	0.1 0 / 0 / 0 / 11	y0 50 03 FF	Off
CAM_SpotAEPosInq	8x 09 04 29 FF	y0 50 0p 0q 0r 0s FF	pg: X Position, rs: Y Position
CAM_SpotAEModeInq	8x 09 04 59 FF	y0 50 02 FF	On
Crivi_SpotriEnvioueniq	0x 0) 04 3) 11	y0 50 03 FF	Off
CAM_VEModeInq	8x 09 04 3D FF	y0 50 03 FF	Off
Critin_ v Elviodeinq	0.07043.011	y0 50 06 FF	VE On
CAM_VEParameterInq	8x 09 04 2D FF	y0 50 00 0q 0r 0s 0t 0u 00 00 FF	q: Display brightness level (0: Dark to 6: Bright) r: Brightness compensation selection (0: Very dark, 1: Dark, 2: Standard, 3: Bright) s: Compensation level (00h: Low, 01h: Mid, 02h: High) tu: Always 0
CAM_AEResponseInq	8x 09 04 5D FF	y0 50 pp FF	pp: 01h to 30h
CAM_DefogInq	8x 09 04 37 FF	y0 50 02 0p FF	p: Defog level (0: mid, 1: low, 2: mid, 3: high)
		y0 50 03 00 FF	Defog Off
CAM_ApertureInq	8x 09 04 42 FF	y0 50 00 00 0p 0q FF	pq: Aperture Gain
CAM_ApertureModeInq	8x 09 05 42 01 FF	x0 50 0p FF	p: Auto (0), Manual (1)
CAM_ApertureBandwidthInq	8x 09 05 42 02 FF	x0 50 0p FF	p: Bandwidth
CAM_ApertureCrispeningInq	8x 09 05 42 03 FF	x0 50 0p FF	p: Crispening
CAM_ApertureH/VBalance	8x 09 05 42 04 FF	x0 50 0p FF	p: H/V Balance
CAM_ApertureB/WBalance	8x 09 05 42 05 FF	x0 50 0p FF	p: B/W Balance
CAM_ApertureLimitInq	8x 09 05 42 06 FF	x0 50 0p FF	p: Limit
CAM_ ApertureHighLightDetailInq	8x 09 05 42 07 FF	x0 50 0p FF	p: High light detail
CAM_ApertureSuperLowInq	8x 09 05 42 08 FF	x0 50 0p FF	p: Super low emphasis
CAM_HRModeInq	8x 09 04 52 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_NRInq	8x 09 04 53 FF	y0 50 0p FF	Noise Reduction p: 00h to 05h, 7Fh
CAM_NR2D3DInq	8x 09 05 53 FF	y0 50 0p 0q FF	p: 2D NR Level, q: 3D NR Level
CAM_StabilizerModeInq	8x 09 04 34 FF	y0 05 02 FF	On
		y0 05 03 FF	Off
CAM_GammaInq	8x 09 04 5B FF	y0 50 0p FF	Gamma p: 00h, 01h
CAM_GammaPatternInq	8x 09 05 5B FF	y0 50 0p 0q 0r FF	pqr: Selection pattern
CAM_GammaOffsetInq	8x 09 04 1E FF	y0 50 00 00 00 0s 0t 0u FF	s: Polarity offset (0 is plus, 1 is minus) tu: Offset s=0 (00h to 40h) Offset s=1 (00h to 10h)
CAM_HighSensitivityInq	8x 09 04 5E FF	y0 50 02 FF	On
		y0 50 03 FF	Off



Inquiry Command List (3/4)

Inquiry Command	Command Packet	Inquiry Packet	Comments	
CAM_LR_ReverseModeInq	8x 09 04 61 FF	y0 50 02 FF	On	
		y0 50 03 FF	Off	
CAM_FreezeModeInq	8x 09 04 62 FF	y0 50 02 FF	On	
		y0 50 03 FF	Off	
CAM_PictureEffectModeInq	8x 09 04 63 FF	y0 50 00 FF	Off	
		y0 50 04 FF	Black & White	
CAM_PictureFlipModeInq	8x 09 04 66 FF	y0 50 02 FF	On	
		y0 50 03 FF	Off	
CAM_ICRModeInq	8x 09 04 01 FF	y0 50 02 FF	On	
		y0 50 03 FF	Off	
CAM_AutoICRModeInq	8x 09 04 51 FF	y0 50 02 FF	On	
		y0 50 03 FF	Off	
CAM_AutoICRThresholdInq	8x 09 04 21 FF	y0 50 00 00 0p 0q FF	pq: ICR On ঢ় Off Threshold Level	
CAM_AutoICRAlarmReplyInq	8x 09 04 31 FF	y0 50 02 FF	On	
		y0 50 03 FF	Off	
CAM_AutoICRAlarmReply	(Reply)	y0 07 04 31 0p FF	p: 2=Off 🖫 On, 3=On 🖫 Off	
CAM_MemoryInq	8x 09 04 3F FF	y0 50 pp FF	pp: Memory number recalled last	
CAM_MemSaveInq	8x 09 04 23 0X FF	y0 50 0p 0q 0r 0s FF	X: 00h to 07h (Address)	
			pqrs: 0000h to FFFFh (Data)	
CAM_DisplayModeInq	8x 09 04 15 FF	y0 50 02 FF	On	
		y0 50 03 FF	Off	
CAM_MuteModeInq	8x 09 04 75 FF	y0 50 02 FF	On	
		y0 50 03 FF	Off	
CAM_SetMaskTableInq	8x 09 05 70 FF	y0 50 0m FF	m: Table	
CAM_PrivacyDisplayInq	8x 09 04 77 FF	y0 50 pp pp pp pFF	pp pp pp pp: Mask Display (0: Off, 1: On)	
CAM_PrivacyPanTiltInq	8x 09 04 79 FF	y0 50 0p 0p 0p 0q 0q 0q FF	ppp: Pan qqq: Tilt	
CAM_PrivacyPTZInq	8x 09 04 7B mm FF	y0 50 0p 0p 0p 0q 0q 0q 0r 0r 0r 0r FF	mm: Mask Settings ppp: Pan qqq: Tilt rrrr: Zoom	
CAM_PrivacyMonitorInq	8x 09 04 6F FF	y0 50 pp pp pp pFF	pp pp pp pp: Mask is displayed now.	
CAM_IDInq	8x 09 04 22 FF	y0 50 0p 0q 0r 0s FF	pqrs: Camera ID	
CAM_VersionInq	8x 09 00 02 FF	y0 50 00 20 mn pq rs tu vw FF	mnpq: Model Code 0709: FCB-ER8530 070A: FCB-ER8550 rstu: ROM version vw: Socket Number (=02)	
CAM_ContinuousZoomPos	8x 09 04 69 FF	y0 50 02 FF	On	
ReplyModeInq		y0 50 03 FF	Off	
CAM_ZoomPosReply IntervalTimeInq	8x 09 04 6A FF	y0 50 00 00 0p 0p FF	pp: Interval Time	
CAM_Continuous	8x 09 04 16 FF	y0 50 02 FF	On	
FocusPosReplyModeInq		y0 50 03 FF	Off	
CAM_ExAutoICROnLevelInq	8x 09 04 1F 21 01 FF	y0 50 00 00 0p 0q FF	pq:Auto ICR Off/On threshold at ICR pq=00h to 1Ch	
CAM_HLCInq	8x 09 04 14 FF	y0 50 0p 0q FF	p: HLC level (0: OFF, 1: low, 2: mid, 3: high) q: HLC mask level (0: OFF, 1 to F: level low to high)	



Inquiry Command List (4/4)

Inquiry Command	Command Packet	Inquiry Packet	Comments
CAM_FocusPosReplyInterval TimeInq	8x 09 04 1A FF	y0 50 00 00 0p 0p FF	pp: Interval Time
(Reply)	-	y0 07 04 16 00 00 0p 0p 0p 0p FF	pppp: Focus Position
CAM_ColorBarInq	8x 09 7E 04 7D FF	y0 50 00 FF	OFF
		y0 50 01 FF	Color bar 100% 8 colors
		y0 50 02 FF	Color bar 100% 7 colors
		y0 50 03 FF	Grayscale
CAM_ePTModeInq	8x 09 7E 06 00 FF	y0 50 02 FF	On
		y0 50 03 FF	Off
CAM_ePTPositionInq	8x 09 7E 06 20 FF	y0 50 00 00 0p 0p 0p 0p 0t 0t 0t 0t	pppp: Pan Position
		FF	tttt: Tilt Position
CAM_TempInq	8x 09 04 68 FF	y0 50 00 00 0p 0p FF	pp: Lens Temperature
CAM_ExExpCompPosInq (Extended Mode)	8x 09 04 1F 4E FF	y0 50 00 00 0p 0p FF	pp: Exposure compensation level
CAM_ExAutoICRThresholdInq (Extended Mode)	8x 09 04 1F 21 00 FF	y0 50 00 00 0p 0p FF	pp: ICR On→Off threshold level when Auto ICR
CAM_ExDetailInq (Extended Mode)	8x 09 04 1F 42 FF	y0 50 00 00 0p 0p FF	pp: Ex Detail Level
CAM_ChromaSuppressInq	8x 09 04 5F FF	y0 50 0p FF	p: Chroma Suppress setting level
CAM_ColorGainInq (Saturation)	8x 09 04 49 FF	y0 50 00 00 00 0p FF	p: Color Gain
CAM_ExColorGainInq (Extended Mode)	8x 09 04 1F 49 00 FF	y0 50 0p 0p FF	pp: Color Gain
CAM_ColorHueInq	8x 09 04 4F FF	y0 50 00 00 00 0p FF	p: Color Hue
CAM_ExColorHueInq (Extended Mode)	8x 09 04 1F 4F 00 FF	y0 50 0p 0p FF	pp: Color Hue
CenterLine	8x 09 04 7C FF	y0 50 0p FF	p: 3=Off, 4=On



Block Inquiry Command List

Lens Control System Inquiry Commands......Command Packet 8x 09 7E 7E 00 FF

Byte	Bit	Comments	Byte	Bit	Comments	
	7			7	0	
	6			6	0	
	5	Destination Address		5	0	
	4			4	0	
0	3		6	3		
	2			2		
	1	Source Address		1	Focus Near Limit (H)	
	0			0		
	7	0 Completion Message (50h)		7	0	
	6	1		6	0	
	5	0		5	0	
	4	1		4	0	
1	3	0	7	3		
	2	0		2		
	1	0		1	Focus Near Limit (L)	
-	0	0		0		
	7	0		7	0	
	6	0		6	0	
	5	0		5	0	
	4	0		4	0	
2	3	•	8	3		
	2			2		
	1	Zoom Position (HH)		1	Focus Position (HH)	
	0			0		
	7	0		7	0	
	6	0		6	0	
	5	0		5	0	
	4	0		4	0	
3	3		9	3		
	2			2		
	1	Zoom Position (HL)		1	Focus Position (HL)	
	0			0		
	7	0		7	0	
	6	0		6	0	
	5	0		5	0	
	4	0		4	0	
4	3	·	10	3	, and the second	
	2			2		
	1	Zoom Position (LH)		1	Focus Position (LH)	
	0			0		
	7	0		7	0	
	6	0		6	0	
	5	0		5	0	
	4	0		4	0	
5	3	U	11	3	, , ,	
	2			2		
	1	Zoom Position (LL)		1	Focus Position (LL)	

Byte	Bit	Comments					
	7	0					
	6	0					
	5	0					
12	4	0					
12	3	0					
	2	0					
	1	0					
	0	0					
	7	0					
	6	Digital Zoom (H)					
	5	DZoomMode 0: Combine					
		1: Separate					
13	4	0: Normal 1: Interval					
15	3	2: Zoom Trigger					
	2	AF Sensitivity 0: Low					
		1: Normal					
	1	Digital Zoom 1: On 0: Off					
	0	Focus Mode 0: Manual 1: Auto					
	7	0					
	6	0					
	5	0					
	4	0					
	3	Low Contrast Detection 1: Yes 0: No					
14	2	Camera Memory Recall					
		1: Executing 0: Stopped					
	1	Focus Command 1: Executing					
		0: Stopped					
	0	Zoom Command 1: Executing 0: Stopped					
	7	1 Terminator (FFh)					
	6	1					
	5	1					
	4	1					
15	3	1					
	2	1					
	1	1					
	0	1					



Camera Control System Inquiry Commands......Command Packet 8x 09 7E 7E 01 FF

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments
	7			7	0		7	0
	6	B 2 2 411		6	0		6	0
	5	Destination Address		5	0		5	0
0	4			4	0	12	4	0
0	3		6	3		12	3	
	2	G A 11		2	WDM 1		2	C : D ::
	1	Source Address		1	WB Mode		1	Gain Position
	0			0			0	
	7	0 Completion Message (50h)		7	0		7	0
	6	1		6	0		6	0
	5	0		5	0		5	0
1	4	1	7	4	0	12	4	
1	3	0	7	3		13	3	
	2	0		2	Amoutuma Cain		2	Bright Position
	1	0		1	Aperture Gain		1	
	0	0		0			0	
	7	0		7	0		7	0
	6	0		6	0		6	0
	5	0		5	0		5	0
2	4	0	0	4	0	14	4	0
2	3		8	3		14	3	
	2	R Gain (H)		2	Exposure Mode		2	Exposure Comp. Position
	1	K Gain (11)		1	Exposure Wode		1	Exposure Comp. I osition
	0			0			0	
	7	0		7	0		7	1 Terminator (FFh)
	6	0		6	0		6	1
	5	0		5	High Resolution 1: On 0: Off		5	1
3	4	0	9	4	VE 1: On 0: Off	15	4	1
3	3			3	Spot AE 1: On 0: Off	13	3	1
	2	R Gain (L)		2	Backlight 1: On 0: Off		2	1
	1	K Guiii (E)		1	Exposure Comp. 1: On 0: Off		1	1
	0			0	Slow Shutter 1: On 0: Off		0	1
	7	0		7	0			
	6	0		6	0			
	5	0		5	0			
4	4	0	10	4				
	3			3				
	2	B Gain (H)		2	Shutter Position			
	1	2 Guin (11)		1				
	0			0				
	7	0		7	0			
	6	0		6	0			
	5	0		5	0			
5	4	0	11	4				
	3		11	3				
	2	B Gain (L)		2	Iris Position			
	1	D Galli (L)		1				



Byte	Bit	Comments	Byte	Bit	Comments
	7			7	0
	6			6	0
	5	Destination Address		5	0
_	4			4	0
0	3		6	3	0
	2			2	0
	1	Source Address		1	0
	0			0	0
	7	0 Completion Message (50h)		7	0
	6	1		6	0
	5	0		5	0
1	4	1	7	4	0
	3	0		3	0
	2	0		2	0
	1	0		1	0
	0	0		0	0
	7	0		7	0
	6	0		6	0
	5	0	8	5	0
2	4	0		4	0
2	3	Auto ICR Alarm (1: On, 0: Off)		3	
	2	Auto ICR 1: On 0: Off		2	G 75 (11)
	1	0		1	Camera ID (HH)
	0	Power 1: On 0: Off		0	
	7	0		7	0
	6	Stabilizer 1: On 0: Off		6	0
	5	0		5	0
2	4	ICR 1: On 0: Off		4	0
3	3	Freeze 1: On 0: Off	9	3	
	2	LR Reverse 1: On 0: Off		2	G
	1	0		1	Camera ID (HL)
	0	0		0	
	7	0		7	0
	6	0		6	0
	5	Privacy Zone 1: On 0: Off		5	0
4	4	Mute 1: On 0: Off	10	4	0
4	3	Title Display 1: On 0: Off	10	3	
	2	Display 1: On 0: Off		2	Comment ID (LII)
	1	0		1	Camera ID (LH)
	0	0		0	
	7	0		7	0
	6	0		6	0
	5	0		5	0
_	4	0	1.1	4	0
5	3		11	3	
	2	D' - 1200 - 125 - 1		2	G 75.33
	1	Picture Effect Mode		1	Camera ID (LL)
ı	0	1		0	

Byte	Bit	Comments			
	7	0			
	6	0			
	5	0			
	4	Memory 1: Provided 0: Not provided			
12	3	0			
12	2	ICR 1: Provided 0: Not provided			
	1	Stabilizer 1: Provided 0: Not provided			
	0	System 1: 1/50, 1/25 0: 1/59.94, 1/29.97			
	7	0			
	6	0			
	5	0			
13	4	0			
13	3	0			
	2	0			
	1	0			
	0	0			
	7	0			
	6	0			
	5	0			
14	4	0			
14	3	0			
	2	0			
	1	0			
	0	0			
	7	1 Terminator (FFh)			
	6	1			
	5	1			
15	4	1			
15	3	1			
	2	1			
	1	1			
	0	1			



Extended Function1 Query Command Command Packet 8x 09 7E 7E 03 FF

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments
	7			7	0		7	0
	6	5		6	0		6	
	5	Destination Address		5	0		5	Color Gain (0h (60%) to
	4			4	0		4	Eh (200%))
0	3		6	3			3	
	2			2		11	2	Advanced Privacy
	1	Source Address		1	AF Interval Time (H)		_	(1: Provided, 0: Not provided)
	0			0			1	Reserved
							0	E-Flip
	7	0 Completion Message (50h)		7	0			(1: Provided, 0: Not provided)
	6	1		6	0		7	0
	5	0		5	0		6	0
1	4	1	7	4	0		5	v
1	3	0	,	3	0		4	
	2	0		2		12	3	
	1	0			AF Interval Time (L)		2	AE Response
				1				
	0	0		0	0		1	
	7	0		7	0		0	
	6	0	8	6	0		7	0
	5	0		5	0		6	
2	4	0		4	0		5	Gamma
	3	Digital Zoom Position (H)		3		13	4	
2	2			2	Spot AE Position (X)		3	High Sensitivity mode
	<i>g</i>		1	~ F *** = = * ****** (* *)			(1: On, 0: Off)	
	0		0		2			
	7	0		7	0		1	NR Level
	6	0		6	0		0	
	5	0		5	0		7	0
2	4	0	9	4	0		6	
3	3		9	3			5	Chroma Suppress
	2	D' '(17 D '(' (1)		2	C (AED 'C (W)	1.4	4	
	1	Digital Zoom Position (L)		1	Spot AE Position (Y)	14	3	
	0			0			2	
	7	0		7	0		1	Gain Limit
	6	0		6	0		0	
	5	0		5	0		7	1 Terminator (FFh)
	4	0		4	0		6	1
4	3		10	3	0		5	1
	2			2	Reserved		4	1
	1	AF Activation Time (H)		1	0	15	3	1
	1			0	E-Flip (1: On, 0: Off)		2	1
	0				r (, , , , , , , , , , , , , , , , , ,		1	1
	7	0						I
	7	0						
	7	0					0	1
	7 6 5	0						
5	7	0						



AF Activation Time (L)

1

Extended Function2 Query Command Command Packet 8x 09 7E 7E 04 FF

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments
	7			7	0		7	0
	6	Destination Address		6	0		6	0
	5	Destination Address		5	0		5	0
0	4		6	4	0	11	4	0
U	3		0	3	0	11	3	0
	2	Source Address		2	0		2	0
	1	Source Address		1	Compensation level		1	0
	0			0	0: Low 1: Mid 2: High		0	0
	7	0 Completion Message (50h)		7	0		7	0
	6	1		6	0		6	0
	5	0		5	0		5	0
1	4	1	7	4	0	12	4	0
1	3	0	,	3	0	12	3	0
	2	0		2	0		2	0
	1	0		1	0		1	0
	0	0		0	Defog 0: Off 1: On		0	0
	7	0		7	0		7	0
	6	0		6	0		6	0
	5	0		5	0		5	0
2	4	0	8	4	0	13	4	0
2	3	0	0	3	0	13	3	0
	2	0		2	0		2	0
	1	VE		1	Defog Level		1	0
	0	0: Off 2: VE On		0	0: mid 1: low 2: mid 3: high		0	0
	7	0		7	0		7	0
	6	0		6	0		6	0
	5	0		5	0		5	0
	4	0		4	0		4	0
3	3	0	9	3	0	14	3	0
	2	0		2	0		2	0
	1	0		1	0		1	0
	0	0		0	0		0	0
	7	0		7	0		7	1 Terminator (FFh)
	6	0		6	0		6	1
	5	0		5	0		5	1
	4	0		4	0		4	1
4	3	0	10	3	0	15	3	1
	2	Display brightness level setting		2	0		2	1
	1	0: Dark to 6: Bright		1	0		1	1
	0	8		0	0		0	1
	7	0			Ÿ		Ĭ	1
	6	0						
	5	0						
	4	0						
5	3	0						
5	2	0						
	1	Brightness compensation selection						
	1	Diffinitess compensation selection						



0: Very dark 1: Dark 2: Standard

3: Bright

Extended Function3 Query Command Command Packet 8x 09 7E 7E 05 FF

Byte	Bit	Comments	Byte	Bit	Comments	Byte	Bit	Comments
	7			7	0		7	0
	6	B 2 2 411		6			6	
	5	Destination Address		5			5	
0	4			4			4	
0	3		6	3	Reserved	11	3	Reserved
	2	G A 11		2			2	
	1	Source Address		1			1	
	0			0			0	
	7	0 Completion Message (50h)		7	0		7	0
	6	1		6			6	
	5	0		5			5	
1	4	1	7	4		12	4	
1	3	0	/	3	Reserved	12	3	Reserved
	2	0		2			2	
	1	0		1			1	
	0	0		0			0	
	7	0		7	0		7	0
	6	0		6		13	6	
	5	0		5			5	
2	4	0	8 4 3 2 1 0	4			4	
2	3			3	Reserved		3	Reserved
	2	Color Hue		2			2	
	1	(0h(-14 degrees) to Eh(+14 degrees))		1			1	
	0			0			0	
	7	0		7	0		7	0
	6			6			6	
	5			5			5	
	4			4			4	
3	3	Reserved	9	3	Reserved 14	3	Reserved	
	2	Reserved		2	Reserved	SSCIVED	2	Reserved
	1			1			1	
	0			0			0	
	7	0		7	0		7	1 Terminator (FFh)
	6			6			6	1
	5			5			5	1
4	4		10	4		15	4	1
4	3	Reserved	10	3	Reserved	13	3	1
	2			2			2	1
	1			1			1	1
	0			0			0	1
	7	0						•
	6							
	5							
	4							
5	3	Reserved						
	2							
	1							



VISCA Command Setting Values

Exposure control (1/3)

		59.94/29.97 mode	50/25 mode	23.98 mode
Shutter Speed/	21	1/10000	1/10000	1/10000
Slow Shutter Limit	20	1/6000	1/6000	1/4800
	1F	1/4000	1/3500	1/2400
	1E	1/3000	1/2500	1/1200
	1D	1/2000	1/1750	1/576
	1C	1/1500	1/1250	1/400
	1B	1/1000	1/1000	1/288
	1A	1/725	1/600	1/200
	19	1/500	1/425	1/192
	18	1/350	1/300	1/144
	17	1/250	1/215	1/120
	16	1/180	1/150	1/100
	15	1/125	1/120	1/96
	14	1/100	1/100	1/60
	13	1/90	1/60	1/50
	12	1/60	1/50	1/48
	11	1/50	1/30	1/40
	10	1/30	1/25	1/25
	0F	1/20	1/20	1/24
	0E	1/15	1/15	1/20
	0D	1/10	1/12	1/12
	0C	1/8	1/8	1/8
	0B	1/6	1/6	1/6
	0A	1/4	1/4	1/4
	09	1/3	1/3	1/3
	08	1/2	1/2	1/2
	07	2/3	2/3	2/3
	06	1/1	1/1	1/1

		59.94/29.97 mode	50/25 mode	23.98 mode
High speed	21	1/10000	1/10000	1/10000
Shutter Limit	20	1/6000	1/6000	1/4800
	1F	1/4000	1/3500	1/2400
	1E	1/3000	1/2500	1/1200
	1D	1/2000	1/1750	1/576
	1C	1/1500	1/1250	1/400
	1B	1/1000	1/1000	1/288
	1A	1/725	1/600	1/200
	19	1/500	1/425	1/192
	18	1/350	1/300	1/144
	17	1/250	1/215	1/120
	16	1/180	1/150	1/100
	15	1/125	1/120	1/96
	14	1/100	1/100	1/60
	13	1/90	1/60	1/50
	12	1/60	1/50	1/48
	11	1/50	1/30	1/40
	10	1/30	1/25	1/25
	0F	-	-	1/24
Slow Shutter	11	1/50	1/30	1/40
Limit	10	1/30	1/25	1/25
	0F	1/20	1/20	1/24
	0E	1/15	1/15	1/20
	0D	1/10	1/12	1/12
	0C	1/8	1/8	1/8
	0B	1/6	1/6	1/6
	0A	1/4	1/4	1/4
	09	1/3	1/3	1/3
	08	1/2	1/2	1/2
	07	2/3	2/3	2/3
	06	1/1	1/1	1/1



Exposure control (2/3)

-		
Iris	19	F2.0
	18	F2.2
	17	F2.4
	16	F2.6
	15	F2.8
	14	F3.1
	13	F3.4
	12	F3.7
	11	F4.0
	10	F4.4
	0F	F4.8
	0E	F5.2
	0D	F5.6
	0C	F6.2
	0В	F6.8
	0A	F7.3
	09	F8
	08	F8.7
	07	F9.6
	06	F10
	05	F11
	00	CLOSE

Gain	11	48 dB
	10	45 dB
	0F	42 dB
	0E	39 dB
	0D	36 dB
	0C	33 dB
	0B	30 dB
	0A	27 dB
	09	24 dB
	08	21 dB
	07	18 dB
	06	15 dB
	05	12 dB
	04	9 dB
	03	6 dB
	02	3 dB
	01	0 dB

0E to $11\ can$ be set only when the high-sensitivity mode is ON.

		High Sensitivity mode		
		Off	On	
Gain Limit	D	36 dB	48 dB	
	С	33 dB	45 dB	
	В	30 dB	42 dB	
	A	27 dB	39 dB	
	9	24 dB	36 dB	
	8	21 dB	33 dB	
	7	18 dB	30 dB	
	6	15 dB	27 dB	
	5	12 dB	24 dB	
	4	9 dB	21 dB	



Exposure control (3/3)

		Iris	Gain
Bright	29	F2.0	48 dB
	28	F2.0	45 dB
	27	F2.0	42 dB
	26	F2.0	39 dB
	25	F2.0	36 dB
	24	F2.0	33 dB
	23	F2.0	30 dB
	22	F2.0	27 dB
	21	F2.0	24 dB
	20	F2.0	21 dB
	1F	F2.0	18 dB
	1E	F2.0	15 dB
	1D	F2.0	12 dB
	1C	F2.0	9 dB
	1B	F2.0	6 dB
	1A	F2.0	3 dB
	19	F2.0	0 dB
	18	F2.2	0 dB
	17	F2.4	0 dB
	16	F2.6	0 dB
	15	F2.8	0 dB
	14	F3.1	0 dB
	13	F3.4	0 dB
	12	F3.7	0 dB
	11	F4.0	0 dB
	10	F4.4	0 dB
	0F	F4.8	0 dB
	0E	F5.2	0 dB
	0D	F5.6	0 dB
	0C	F6.2	0 dB
	0B	F6.8	0 dB
	0A	F7.3	0 dB
	09	F8.0	0 dB
	08	F8.7	0 dB
	07	F9.6	0 dB
	06	F10	0 dB
	05	F11	0 dB
	00	CLOSE	0 dB
26 to 29 can be set only	when the	high-sensitivity	mode is ON

26 to 29 can be set only	when the hig	h-sensitivity mod	de is ON.
--------------------------	--------------	-------------------	-----------

Exposure Comp.	0E	+7	+10.5 dB
	0D	+6	+9 dB
	0C	+5	+7.5 dB
	0B	+4	+6 dB
	0A	+3	+4.5 dB
	09	+2	+3 dB
	08	+1	+1.5 dB
	07	0	0 dB
	06	-1	−1.5 dB
	05	-2	−3 dB
	04	-3	-4.5 dB
	03	-4	−6 dB
	02	-5	−7.5 dB
	01	-6	−9 dB
	00	-7	-10.5 dB
· · · · · · · · · · · · · · · · · · ·			·

Zoom Ratio and Zoom Position (for reference)

Optical Zoom Ratio	Optical Zoom Position Data	
1×	0000	
2×	0DC1	
3×	186C	
4×	2015	
5×	2594	
6×	29B7	
7×	2CFB	
8×	2FB0	
9×	320C	
10×	342D	
11×	3608	
12×	37AA	
13×	391C	
14×	3A66	
15×	3B90	
16×	3C9C	
17×	3D91	
18×	3E72	
19×	3F40	
20×	4000	



Digital Zoom Combine mode

Digital Zoom Ratio	Digital Zoom Position Data	
1×	4000	
2×	6000	
3×	6AAB	
4×	7000	
5×	7334	
6×	7556	
7×	76DC	
8×	7800	
9×	78E4	
10×	799A	
11×	7A2F	
12×	7AC0	

Digital Zoom Separate mode

Digital Zoom Ratio	Digital Zoom Position Data
1×	00
2×	80
3×	AA
4×	C0
5×	CC
6×	D5
7×	DB
8×	E0
9×	E3
10×	E6
11×	E8
12×	EB

Lens control

	0000 to 4000 to 7AC0
Zoom Position	wide end Optical Digital
Zoom rosition	tele end tele end
	1000 to F000
Focus Position	Far end Near end
	1000: Inf
	2000: 5 m
	3000: 3 m
	4000: 2 m
	5000: 1.5 m
	6000: 1.2 m
	7000: 1.0 m As the distance on the left
Focus Near	will differ due to temperature characteristics, etc., use as
Limit	9000: 0.6 m approximate values.
	A000: 47 cm *The lower 1 byte is fixed at 00.
	B000: 35 cm
	(initial setting)
	C000: 26 cm
	D000: 17 cm
	E000: 10 cm
	F000: 8 cm

wide/tele Limit Setting

wide/tele Limit	wide Limit		tele Limit	
	Zoom	Zoom	Zoom	Zoom
Setting Value	Position	Ratio	Position	Ratio
00	0000	1.00	4000	20.00
10	0170	1.09	3E8F	18.14
20	02E0	1.18	3D1F	16.53
30	0450	1.28	3BAF	15.12
40	05C0	1.38	3A3F	13.89
50	0730	1.47	38CF	12.80
60	08A1	1.58	375E	11.83
70	0A11	1.69	35EE	10.96
80	0B81	1.81	347E	10.18
90	0CF1	1.94	32F7	9.44
A0	0E61	2.07	319E	8.83
В0	0FD1	2.19	302E	8.22
C0	1142	2.32	2EBD	7.65
D0	12B2	2.44	2D4D	7.13
E0	1422	2.58	2BDD	6.66
F0	1592	2.72	2A6D	6.22
FF	16EB	2.85	2914	5.85



Temperature Reading Conversion Value (Reference Value)

Reading Value pq (hex)	Temperature Conversion Value (°C)
FB	−8 to −2
00	−3 to +3
0A	7 to 13
14	17 to 23
1E	27 to 33
28	37 to 43
32	47 to 53
3C	57 to 63

Register Setting

The register settings are enabled when the power is turned off and then back on again. After turning the power back on again, verify that the mode settings have been changed.

Note

If you switch to PTP with switching VISCA/USB_PTP, you can no longer communicate with VISCA after that.

When switching to VISCA, switch to VISCA with PTP control. For the PTP control, refer to "FCB Remote Camera Control Specification for PTP".

	I		
	Register No.	Value	
VISCA	00	00	9600 bps
Baud Rate		(Initial Setting)	
		01	19200 bps
		02	38400 bps
		03	57600 bps
		04	115200 bps
Switching	01	00	VISCA
VISCA/		(Initial	
USB_PTP		Setting: 00)	
		01	USB_PTP
Digital	60	00	YUV
Output		(Initial Setting)	
		01	RGB

	Register No.	Value	
Monitoring	72	1D	System: QFHD
Mode		(Initial Setting)	(3840 × 2160) 29.97p
			Output: 3840 × 2160 29.97p
			1920 × 1080 29.974p
			When electronic pan/tilt is
			ON.
		1E	System: QFHD
			(3840 × 2160) 25p
			Output: 3840 × 2160 25p
			1920 × 1080 25p
			When electronic pan/tilt is
			ON.
		20	System: QFHD
			(3840 × 2160) 23.98p
			Output: 3840 × 2160 23.98p
			1920×1080 50p
			When electronic pan/tilt is
		10	ON.
		13	System: FHD (1920 × 1080)
			59.94p
		14	Output: 1920 × 1080 59.94p
		14	System: FHD (1920 × 1080) 50p
			Output: 1920 × 1080 50p
		01	System: FHD (1920 × 1080)
		01	59.94i
			Output: 1920 × 1080 59.94i
		04	System: FHD (1920 × 1080)
			50i
			Output: 1920 × 1080 50i
		06	System: FHD (1920 × 1080)
			29.97p
			Output: 1920 × 1080 29.97p
		08	System: FHD (1920 × 1080)
			25p
			Output: 1920 × 1080 25p
		1F	System: FHD (1920 × 1080)
			23.98p
			Output: 1920 × 1080 23.98p
		09	System: HD (1280 × 720)
			59.94p
		0.7	Output: 1280 × 720 59.94p
		0C	System: HD (1280 × 720) 50p
		10	Output: 1280 × 720 50p
		1B	System: SD (720 × 480) 59.94p
		10	Output: 720 × 480 59.94p
		1C	System: SD (720 × 576) 50p
			Output: 720 × 576 50p

The frame rate of system in the monitoring mode is the screen update interval.



	Register No.	Value	
Zoom Limit	50	00-FF	Wide Limit
		(Initial Setting: 00)	(0: Disabled)
	51	00-FF	Tele Limit
		(Initial Setting: 00)	(0: Disabled)
D-Zoom Max	52	00-EB	Max. digital
		(Initial Setting: EB)	zoom ratio =
			256 ÷ (256-Value)
"StableZoom"	53	00	Off
		(Initial Setting: 00)	
		01	On
APR	56	00	On start-up APR
		(Initial Setting: 00)	OFF
		01	On start-up APR
			ON
FocusOffset	55	00-FF	00: None to
@DomeCover		(Initial Setting: 00)	FF: Max.
Extended	5F	00	0FF
Mode		bit: 0 Exposure com	pensation
		Extended 256 levels	On/Off
		bit: 1 Aperture Exte	nded 256 levels
		On/Off	
		bit: 2 Color Gain/Hue Extended 256	
		levels On/Off	
		bit: 3 Auto ICR Off 🖟 On setting	
		enable On/Off	
		*For all of bit, 1 is to activate, 0 is Off	

Others

AF Active Time1)	00	to	FF
AF Interval Time ¹⁾	00	to	FF
Spot AE X position	00	to	0F
Spot AE Y position	00	to	0F
R Gain	00	to	FF
B Gain	00	to	FF
Aperture Control Level	00	to	0F
AE Response	01	to	30
AutoICR On 🖟 Off Threshold Level	00	to	FF
Chroma Suppress setting level	00	to	03
Color Gain setting level	00	to	0E
Color Hue setting level	00	to	0E

¹⁾ Unit: One second



USB commands for firmware update

Basic specifications of commands and response

- Communication is performed in units of packets.
- The packet consists of a header (32 bytes) and body (from 0 byte).
- Two types of packets in a command and response are defined as described below.
- Command Data transfer of a host to this unit
- Response Data transfer of this unit to a host
- One response packet is necessarily returned to one command packet.
 - * However, there is no response in a specific command.
- Byte array is based on a little-endian format.

■ Description of notation

Notation of type

uint: Unsigned integer (Does not depend on the

data length.)

Binary: Binary data string

■Packet structure

The packet consists of a fixed-length (32-byte) header and size-variable body.

The maximum packet size is prescribed for each command or during communication parameter

setting.

Data array	Size [Byte]	Туре
Packet{		
Packet Header	32	Packet Header
Body	n	Binary
}		

■ Packet Header (Common in both a command and response)

Data array	Size [Byte]	Туре
Packet Header{		
BodySize	4	uint
Protocol Version	2	uint
Command ID	2	uint
Response ID	2	uint
Sequence No.	2	uint
reserved	4	uint
reserved	4	uint
reserved	4	uint
reserved	8	uint
}		

■ Meaning

Body Size

This is the size of a body following a packet header. (The size of a packet header is not contained.)

Protocol Version

This is the version of a communication protocol. Fixed to 0x0100.

(The host sets the protocol version contained in firmware data.)

Command ID

Command packet: Sets the command to be

executed.

Response packet: The same value as the

corresponding command

packet is set.

Response ID

Command packet: Fixed to 0x0000.

Response packet: ID indicating the processing

result of the corresponding

command

For more details, refer to the specifications for each

command. (See pages 58 to 62.)

Sequence No.

Command packet: Sequence number unique in all

commands

Returned to 1 when an overflow

occurs in the range of 1 to

65536.

Response packet: Returns the sequence number

of the corresponding command

as it is.

An error does not especially occur even when the value of a sequence number is skipped.

■ Body

Data used as each command and response parameter is stored.

The body varies depending on each command and response.



ID list

Command ID	Definition of ID	Outline description
/*Initial communicatio	n*/	·
0x0001	CMD_INIT	Initializes communication.
/*Judgment of rush cor	nditions*/	
0x0010	CMD_CHK_GUARD	Starts the judgment of rush conditions.
/*Inquiry of firmware v	version*/	
0x0020	CMD_QUERY_VERSION	Inquires the version of firmware.
/*Start mode switching	request*/	
0x0030	CMD_SWITCH_MODE	Executes the switching to a firmware update mode.
/*Firmware rewrite*/		
0x0040	CMD_WRITE_FIRM	Transfers firmware data and writes it.
/*Completion check no	otification of rewrite processing*/	
0x0100	CMD_COMPLETE	Notifies the completion check of firmware update.
/*Acquisition of firmw	rare update processing status in this unit*/	
0x0200	CMD_GET_STATE	Acquires the firmware update processing status.

Response ID	Definition of ID (STAT_ is also the same.)	Outline description (The detailed meaning varies depending on each command.)
/*Normal system*/		
0x0001	ERR_OK	Normal termination
0x0002	ERR_BUSY	Processing in progress
/*Communication prote	ocol error*/	
0x0100	ERR_PROV	Difference in protocol version
0x0101	ERR_SEQUENCE	Sequence error. This is not a state in which a command can be received.
0x0102	ERR_BIG	A packet is too large. (A receive buffer is insufficient.)
0x0103	ERR_INVALID_PARAM	A parameter is illegal.
/*0x1xxx: Processing e	rror in this unit*/	
0x1xxx	ERR_INTERNAL	Internal processing error in this unit

Response ID	Definition of ID	Outline description (The detailed meaning varies depending on each command.)
/*Normal system*/		
0x0001	STAT_OK	
0x0002	STAT_BUSY	
/*Status of rush condition	s*/	
0x0140	STAT_INVALID_MODEL	A model differs.
0x0141	STAT_INVALID_REGION	Destination differs.
/*Firmware data error*/		
0x0040	STAT_INVALID_DATA	The received firmware data is illegal (damaged).
		(The data is falsified and cannot be detected by CRC of a package file.)

A processing error in this unit is notified to a ResponseID field as an error.

CurStatus ID	Definition of ID	Outline description
0x0100	CURSTAT_PRE_INIT	Before CMD_INIT reception
0x0200	CURSTAT_PRE_SWITCHMODE	After CMD_SWITCHMODE reception



Command specifications

Command	Description						
CMD_GET_STATE	■ Outline						
	This command acquires the firmware update processing status in this unit.						
	*This command can be accepted at any time	when communication i	s established.				
	■ Command parameter						
	None						
	Response (ID/Parameter)						
	_	ERR_OK					
	Initialization succeeded. The subsequent maximum packet size and minimum time-out are turned to a parameter.						
	Parameter →			<u></u>			
	Parameter data arrangement	Size [Byte]	Туре				
	OK Parameter{						
	currentState ID	2	uint				
	}						
	J						
	■ Meaning						
	currentState ID						
	This is the set state at the point of ti	ime where a command v	vas received				
	Refer to the ID list of each STAT ID		vas recerved.				
			DC 1' '	CMD DUT			
				issues a CMD_INIT command			
	CURST AT_SWITCHMODE Dur	ring mode switching (St	ate in which a cor	nmand cannot be returned by INI			
	*Fr	om when PC application	issues a CMD_S	WITCH_MODE command			
	ERR_PROV						
	This cannot be used for the communicat	ion protocol version set	to a packet heade	r.			
	This cannot be used for the communication protocol version set to a packet header. No parameter						
	■ Remarks						
MD_INIT	• Outline						
	This command initializes communication a This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter)	tial state by receiving th					
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK	tial state by receiving th ot be received.	e parameter.				
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter)	tial state by receiving th ot be received.	e parameter.	ne-out are turned to a parameter.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK	tial state by receiving th ot be received.	e parameter.	ne-out are turned to a parameter.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen	tial state by receiving th ot be received. t maximum packet size	e parameter.	ne-out are turned to a parameter.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter →	tial state by receiving th ot be received.	e parameter.	ne-out are turned to a parameter.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{	tial state by receiving th ot be received. t maximum packet size Size [Byte]	e parameter. and minimum tim Type	ne-out are turned to a parameter.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize	tial state by receiving the ot be received. t maximum packet size Size [Byte]	e parameter. and minimum tim Type uint	ne-out are turned to a parameter.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4	e parameter. and minimum tim Type uint uint	ne-out are turned to a parameter.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4 4	and minimum tim Type uint uint uint	ne-out are turned to a parameter.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4 4 4	and minimum tim Type uint uint uint uint uint	ne-out are turned to a parameter.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4 4	and minimum tim Type uint uint uint	ne-out are turned to a parameter.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4 4 4	and minimum tim Type uint uint uint uint uint	ne-out are turned to a parameter.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse }	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4 4 4	and minimum tim Type uint uint uint uint uint	ne-out are turned to a parameter.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } Meaning	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4 4 4	and minimum tim Type uint uint uint uint uint	ne-out are turned to a parameter.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } Meaning maxCmdPacketSize	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4 4 4 4	and minimum tim Type uint uint uint uint uint uint				
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } Meaning	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4 4 4 4	and minimum tim Type uint uint uint uint uint uint				
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } Meaning maxCmdPacketSize	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4 4 4 4 4 0 9 0 9 0 9 0 9 0 9 0 9	and minimum tim Type uint uint uint uint uint uint				
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } Meaning maxCmdPacketSize This is the maximum packet size [b]	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4 4 4 4 4 0 9 0 9 0 9 0 9 0 9 0 9	and minimum tim Type uint uint uint uint uint uint				
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } Meaning maxCmdPacketSize This is the maximum packet size [the Not including a CMD_GET_STATE maxResPacketSize]	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4 4 4 9 oyte] of a command packet command	and minimum time. Type uint uint uint uint uint uint uint uin	ion has succeeded.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } Meaning maxCmdPacketSize This is the maximum packet size [b Not including a CMD_GET_STAT maxResPacketSize This is the maximum packet size [b	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4 4 4 9 oyte] of a command packet command	and minimum time. Type uint uint uint uint uint uint uint	ion has succeeded.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } Meaning maxCmdPacketSize This is the maximum packet size [the Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [the MotintimeOut] This is the maximum packet size [the MotintimeOut]	tial state by receiving the ot be received. It maximum packet size Size [Byte] 4 4 4 4 4 9 Oyte] of a command packet size	and minimum tim Type uint uint uint uint uint et after initializate	ion has succeeded.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter { maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } Meaning maxCmdPacketSize This is the maximum packet size [the Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [the Motincluding a CMD_GET_STATE maxResPacketSize This is the maximum packet size [the Motincluding a CMD_GET_STATE maxResPacketSize This is the minimum timeout time	tial state by receiving the ot be received. It maximum packet size Size [Byte] 4 4 4 4 4 9 Oyte] of a command packet size	and minimum tim Type uint uint uint uint uint et after initializate	ion has succeeded.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } Meaning maxCmdPacketSize This is the maximum packet size [the Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [the MotintimeOut] This is the maximum packet size [the MotintimeOut]	tial state by receiving the ot be received. It maximum packet size Size [Byte] 4 4 4 4 4 9 Oyte] of a command packet size	and minimum tim Type uint uint uint uint uint et after initializate	ion has succeeded.			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter { maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } Meaning maxCmdPacketSize This is the maximum packet size [the Not including a CMD_GET_STATE maxResPacketSize This is the maximum packet size [the Motincluding a CMD_GET_STATE maxResPacketSize This is the maximum packet size [the Motincluding a CMD_GET_STATE maxResPacketSize This is the minimum timeout time	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4 4 4 Country of a command packet size and packet size are sponse packet size are sponse packet size and packet size are sponse packet size and packet size are sponse packet size are sponse packet size and packet size are sponse	and minimum time. Type uint uint uint uint uint et after initialization command after of	ion has succeeded. on has succeeded. communication initialization has			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize maxResPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } Meaning maxCmdPacketSize This is the maximum packet size [the Not including a CMD_GET_STATT maxResPacketSize This is the maximum packet size [the minTimeOut This is the minimum timeout time succeeded.	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4 4 4 Country of a command packet size and packet size are sponse packet size are sponse packet size and packet size are sponse packet size and packet size are sponse packet size are sponse packet size and packet size are sponse	and minimum time. Type uint uint uint uint uint et after initialization command after of	ion has succeeded. on has succeeded. communication initialization has			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } Meaning maxCmdPacketSize This is the maximum packet size [the Not including a CMD_GET_STATM maxResPacketSize This is the maximum packet size [the Not including a CMD_GET_STATM maxResPacketSize This is the minimum timeout time succeeded. The host must time out using a valintervalBeforeCommand	tial state by receiving the ot be received. It maximum packet size Size [Byte] 4 4 4 4 4 9 Oyte] of a command packet command Oyte] of a response packet [msec] common to each use of more than the minuse.	and minimum time. Type uint uint uint uint uint uint and minimum time. tuint uint uint uint uint uint uint ui	ion has succeeded. on has succeeded. communication initialization has			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } Meaning maxCmdPacketSize This is the maximum packet size [the Not including a CMD_GET_STAT] maxResPacketSize This is the maximum packet size [the MinTimeOut] This is the minimum timeout time succeeded. The host must time out using a valintervalBeforeCommand This is the min time [msec] require	tial state by receiving the ot be received. It maximum packet size Size [Byte] 4 4 4 4 4 9 Oyte] of a command packet command Oyte] of a response packet [msec] common to each use of more than the minuse.	and minimum time. Type uint uint uint uint uint uint and minimum time. tuint uint uint uint uint uint uint ui	ion has succeeded. on has succeeded. communication initialization has			
	This unit returns the internal state to the init There is a state in which the parameter cann Command parameter None Response (ID / Parameter) ERR_OK Initialization succeeded. The subsequen Parameter → Parameter data arrangement OK Parameter{ maxCmdPacketSize minTimeOut intervalBeforeCommand intervalBeforeResponse } Meaning maxCmdPacketSize This is the maximum packet size [the Not including a CMD_GET_STATM maxResPacketSize This is the maximum packet size [the Not including a CMD_GET_STATM maxResPacketSize This is the minimum timeout time succeeded. The host must time out using a valintervalBeforeCommand	tial state by receiving the ot be received. t maximum packet size Size [Byte] 4 4 4 4 9 Oyte] of a command packet command oyte] of a response packet [msec] common to each ue of more than the mineral of from when the host response packet of the command of the common to each up the common to each up the common to each of	and minimum time. Type uint uint uint uint uint uint uint uin	ion has succeeded. on has succeeded. communication initialization has ne. until it issues the next command.			



Command	Description				
CMD_INIT	ERR_PROV				
	This cannot be used for the communication protocol version set to a packet header.				
	No parameter				
	ERR_SEQUENCE				
	Communication sequence error. No	parameter.			
	This is a state in which a CMD_IN	IT command cannot be red	ceived.		
	■ Remarks				
CMD_CHK_GUARD	■ Outline				
	This command starts the confirmation	processing of rush condit	ions.		
	■ Command parameter				
	Parameter data arrangement	Size [Byte]	Туре		
	CHK_GUARD Parameter{	Size [Byte]	1,700		
	dataNo	4	uint		
	remainSize	4	uint		
	firmData	dataSize	Binary		
	111111111111111111111111111111111111111	dataSize	Dillary		
	[]				
	■ Meaning				
	dataNo.				
	This is the number of times by wl	hich this command was iss	sued to confirm rush c	onditions. "0" is not used.	
	Increment this from 1 irrespective	e of the existence of firmD	ata.		
	remainSize				
	This is the size of firmware data t	hat has not been transmitte	ed vet. (The data size l	pecomes zero during final	
	This is the size of firmware data that has not been transmitted yet. (The data size becomes zero during final				
	transfer.) This gives compatibility with the WRITE_FIRM command described later.				
	firmData	WKITE_I IKWI command	described later.		
		on of firmayyone data (the da	oto division of "EDAT	" should is sulit for transfer. The	
	To confirm rush conditions, the top of firmware data (the data division of "FDAT" chunk) is split for transfer. The size of data to be transferred is specified by windowSize. Operation is completed when STAT_OK is returned.				
		ecified by windowSize. Of	peration is completed v	when STAT_OK is returned.	
	*See pages 65 and 66.				
	■ Response	(ID/Parameter)			
	Common parameter that does not vary		D		
	Parameter data arrangement	t Size [Byte]	Туре		
	Response Parameter{				
	windowSize	4	uint		
	numStatus	4	uint		
	for (i = 0; i < numStatus; i++){				
	Status ID	2	uint		
	}				
	{				
	L				
	■ Meaning				
	windowSize				
	This is the size	of firmData	that this ur	nit can receive.	
	A packet (including fir	mData) of less t	han windowSize	can be received.	
		$xe \ge 32$ [byte] header + where	indowSize + 8 (parame	eters other than firmData).	
	It is necessary to satisfy packetSize ≥ 32 [byte] header + windowSize + 8 (parameters other than firmData). numStatus				
	This is the number of status IDs following numStatus.				
	Status ID	ono ming numbratus.			
		itions			
	Confirmation result of rush condi				
	STAT_OK	Conditions are satisfied.			
	STAT_BUSY	Processing in progress			
	STAT_INVALID_MODEL	A model differs.			
	STAT_INVALID_REGION	Destination differs.			
	STAT_INVALID_DATA	Firmware data is damage	ed.		
	For OK and Busy, this is necessar				
	ERR_OK				
	A command was received normally				
	ERR_PROV	•			
		nication protocol vorcion	set to a packet handa-		
	This cannot be used for the commu	meanon protocor version	sei io a paekei lleader.		
	No parameter				



	Description					
CMD_CHK_GUARD	ERR_SEQUENCE					
	Communication sequence error. No parameter.					
	This cannot be received before communication is initialized.					
	ERR_BIG					
	Packet size is too large.					
	ERR_INVALID_PARAM					
	dataNo is invalid. (A value is skipped.) dat	taSize is invalid.				
	Errors other than described above are process					
CMD_QUERY_VERSION	■ Outline			-		
	This command inquires the version of new ar	nd old firmware.				
	■ Command parameter					
	None					
	■ Response (ID/Parameter)					
	ERR_OK					
	Normal termination. The version of new a	and old firmware is retu	rned using a parameter	f.		
	Parameter →					
	Parameter data arrangement	Size [Byte]	Туре			
	OK Parameter{		7,40			
	oldFirmMinorVersion	2	uint			
	oldFirmMajorVersion	2	uint			
	newFirmMinorVersion	2	uint			
	newFirmMajorVersion	2	uint			
	}	_				
	J					
	■ Meaning					
	oldFirmMinorVersion					
	oldFirmMajorVersion					
	Minor and major version numbers o	f old firmware				
	newFirmMinorVersion					
	newFirmMajorVersion					
	Minor and major version numbers of new firmware					
	Fixed to 0x0000 before rush condition	ons are confirmed. \rightarrow Tl	ne version is not known	yet.		
		ERR_PROV				
	ERR_PROV					
	ERR_PROV This cannot be used for the communication	on protocol version set t	o a packet header.			
	_	on protocol version set t	o a packet header.			
	This cannot be used for the communication	on protocol version set t	o a packet header.			
	This cannot be used for the communication No parameter		o a packet header.			
	This cannot be used for the communication No parameter ERR_SEQUENCE	neter.	o a packet header.			
	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter	neter. cation is initialized.	o a packet header.			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication	neter. cation is initialized.	o a packet header.			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processing the communication of the communication sequence error.	meter. cation is initialized. ng errors in this unit.	o a packet header.			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processing of the pr	meter. cation is initialized. ng errors in this unit.	o a packet header.			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communications other than described above are processing Outline This command performs switching to a firmy	meter. cation is initialized. ng errors in this unit.	o a packet header.			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processing outline. Outline This command performs switching to a firmy Command parameter.	meter. cation is initialized. ng errors in this unit.	o a packet header.			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parametric This cannot be accepted before communication sequence are processing outline. I Outline This command performs switching to a firmy Command parameter.	meter. cation is initialized. ng errors in this unit.	o a packet header.			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processing of the communication of the communica	meter. cation is initialized. ng errors in this unit. ware update mode.				
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processing outline. This command performs switching to a firm of the command parameter. None Response (ID/Parameter) ERR_OK	meter. cation is initialized. ng errors in this unit. ware update mode.				
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processing outline This command performs switching to a firmy Command parameter None Response (ID/Parameter) ERR_OK A firmware update mode switching communication Parameter →	meter. cation is initialized. ng errors in this unit. ware update mode. nand is received normal	ly.			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parametric This cannot be accepted before communication sequence are processing and the sequence of the sequence error. No parameter the sequence error er	meter. cation is initialized. ng errors in this unit. ware update mode.				
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processing of the command performs switching to a firm of the command parameter None Response (ID/Parameter) ERR_OK A firmware update mode switching communication parameter → Parameter data arrangement OK Parameter{	meter. cation is initialized. ng errors in this unit. ware update mode. and is received normal	ly.			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processing. ■ Outline This command performs switching to a firm of the command parameter None Response (ID/Parameter) ERR_OK A firmware update mode switching communication Parameter → Parameter data arrangement OK Parameter of the communication of the	meter. cation is initialized. ng errors in this unit. ware update mode. and is received normal Size [Byte]	ly. Type uint			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processin Outline This command performs switching to a firmy Command parameter None Response (ID/Parameter) ERR_OK A firmware update mode switching communication Parameter → Parameter data arrangement OK Parameter{ reserved = 0 numStatus = 1	meter. cation is initialized. ng errors in this unit. ware update mode. and is received normal Size [Byte] 4 4	Type uint uint			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processing. ■ Outline This command performs switching to a firm of the command parameter None Response (ID/Parameter) ERR_OK A firmware update mode switching communication Parameter → Parameter data arrangement OK Parameter of the communication of the	meter. cation is initialized. ng errors in this unit. ware update mode. and is received normal Size [Byte]	ly. Type uint			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processin Outline This command performs switching to a firmy Command parameter None Response (ID/Parameter) ERR_OK A firmware update mode switching communication Parameter → Parameter data arrangement OK Parameter{ reserved = 0 numStatus = 1	meter. cation is initialized. ng errors in this unit. ware update mode. and is received normal Size [Byte] 4 4	Type uint uint			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processin Outline This command performs switching to a firmy Command parameter None Response (ID/Parameter) ERR_OK A firmware update mode switching communication Parameter → Parameter data arrangement OK Parameter{ reserved = 0 numStatus = 1	meter. cation is initialized. ng errors in this unit. ware update mode. and is received normal Size [Byte] 4 4	Type uint uint			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication of the communicati	meter. cation is initialized. ng errors in this unit. ware update mode. and is received normal Size [Byte] 4 4	Type uint uint			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processin ■ Outline This command performs switching to a firmy ■ Command parameter None ■ Response (ID/Parameter) ERR_OK A firmware update mode switching communication parameter → Parameter data arrangement OK Parameter{ reserved = 0 numStatus = 1 Status ID } ■ Meaning	meter. cation is initialized. ng errors in this unit. ware update mode. and is received normal Size [Byte] 4 4 2	Type uint uint uint			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processinal outline This command performs switching to a firmy Command parameter None Response (ID/Parameter) ERR_OK A firmware update mode switching communication Parameter → Parameter data arrangement OK Parameter{ reserved = 0 numStatus = 1 Status ID } Meaning numStatus	meter. cation is initialized. ng errors in this unit. ware update mode. and is received normal Size [Byte] 4 4 2	Type uint uint uint			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processinal outline This command performs switching to a firmy Command parameter None Response (ID/Parameter) ERR_OK A firmware update mode switching communication Parameter → Parameter data arrangement OK Parameter{ reserved = 0 numStatus = 1 Status ID } Meaning numStatus This is the number of statuses follow Status ID	meter. cation is initialized. ng errors in this unit. ware update mode. and is received normal Size [Byte] 4 4 2	Type uint uint uint uint			
CMD_SWITCH_MODE	This cannot be used for the communication No parameter ERR_SEQUENCE Communication sequence error. No parameter This cannot be accepted before communication sequence are processinal outline This command performs switching to a firmy Command parameter None Response (ID/Parameter) ERR_OK A firmware update mode switching communication Parameter → Parameter data arrangement OK Parameter{ reserved = 0 numStatus = 1 Status ID } Meaning numStatus This is the number of statuses follow Status ID	meter. cation is initialized. ng errors in this unit. ware update mode. size [Byte] 4 4 2 ving numStatus. (Fixed to cessing is terminated not continuous and continuo	Type uint uint uint uint			



	Description				
CMD_SWITCH_MODE	ERR_PROV				
	This cannot be used for the communication protocol version set to a packet header.				
	No parameter				
	ERR_SEQUENCE				
	Communication sequence error. No p	arameter.			
	_		t is in operation and when rush conditions are not		
	established.	phonon of the main se	tion operation and when rush conditions are not		
	Errors other than described above are in-s	set errors.			
MD_WRITE_FIRM	■ Outline				
	This command rewrites firmware.				
	■ Command parameter				
	Parameter data arrangement	Size [Byte]	Туре		
	WRITE_FIRM Parameter{	- 7 -			
	dataNo	4	uint		
	remainSize	4			
		4	uint		
	firmData		Binary		
	}				
	■ Meaning				
	dataNo				
		1.41	1		
			sued to transfer firmware data. "0" is not used.		
	This is incremented every time firm				
	This is reset by initialization of com	munication.			
	remainSize				
	This is the size of firmware data that	t has not been transmitt	ed yet. (The data size becomes zero during final		
	transfer.)		•		
	firmData				
	firmData Firmware data (the data division of "FDAT" chunk) is split for transfer.				
		FDA1 chunk) is split	for transfer.		
	*See pages 65 and 66.				
	■ Response	(ID/Parameter)			
	Common parameter that does not vary de	epending on response I	D		
	Parameter data arrangement	Size [Byte]	Туре		
		7.2	71-		
	Response Parameter {	4	wint		
	windowSize	4	uint		
	windowSize numStatus = 1		uint		
	windowSize	2	uint		
	windowSize numStatus = 1		uint		
	windowSize numStatus = 1 Status ID }		uint		
	windowSize numStatus = 1 Status ID Meaning		uint		
	windowSize numStatus = 1 Status ID }		uint		
	windowSize numStatus = 1 Status ID Meaning		that this unit can receive.		
	windowSize numStatus = 1 Status ID Meaning windowSize	of firmData			
	windowSize numStatus = 1 Status ID } Meaning windowSize This is the size A packet (including firmI	of firmData Data) of less	that this unit can receive. than windowSize can be received.		
	windowSize numStatus = 1 Status ID Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize	of firmData Data) of less	that this unit can receive.		
	windowSize numStatus = 1 Status ID Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID	of firmData Data) of less	that this unit can receive. than windowSize can be received.		
	windowSize numStatus = 1 Status ID Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize	of firmData Data) of less	that this unit can receive. than windowSize can be received.		
	windowSize numStatus = 1 Status ID Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status	of firmData Data) of less ≥ 32 [byte] header + w	that this unit can receive. than windowSize can be received.		
	windowSize numStatus = 1 Status ID Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status STAT_OK Firmw	of firmData Data) of less ≥ 32 [byte] header + w	that this unit can receive. than windowSize can be received. indowSize + 8 (parameters other than firmData).		
	windowSize numStatus = 1 Status ID } • Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status STAT_OK Firmw STAT_BUSY Proces	of firmData Data) of less ≥ 32 [byte] header + w vare rewrite processing sing in progress	that this unit can receive. than windowSize can be received. indowSize + 8 (parameters other than firmData).		
	windowSize numStatus = 1 Status ID } Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status STAT_OK Firmw STAT_BUSY Proces STAT_INVALID_DATA Firmw	of firmData Data) of less ≥ 32 [byte] header + w vare rewrite processing	that this unit can receive. than windowSize can be received. indowSize + 8 (parameters other than firmData).		
	windowSize numStatus = 1 Status ID } Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status STAT_OK Firmw STAT_BUSY Proces STAT_INVALID_DATA Firmw ERR_OK	of firmData Data) of less ≥ 32 [byte] header + w vare rewrite processing sing in progress vare data is damaged.	that this unit can receive. than windowSize can be received. indowSize + 8 (parameters other than firmData).		
	windowSize numStatus = 1 Status ID Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status STAT_OK Firmw STAT_BUSY Proces STAT_INVALID_DATA Firmw ERR_OK Firmware data was received normally.	of firmData Data) of less ≥ 32 [byte] header + w vare rewrite processing sing in progress vare data is damaged.	that this unit can receive. than windowSize can be received. indowSize + 8 (parameters other than firmData).		
	windowSize numStatus = 1 Status ID } Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status STAT_OK Firmw STAT_BUSY Proces STAT_INVALID_DATA Firmw ERR_OK	of firmData Data) of less ≥ 32 [byte] header + w vare rewrite processing sing in progress vare data is damaged.	that this unit can receive. than windowSize can be received. indowSize + 8 (parameters other than firmData).		
	windowSize numStatus = 1 Status ID Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status STAT_OK Firmw STAT_BUSY Proces STAT_INVALID_DATA Firmw ERR_OK Firmware data was received normally.	of firmData Data) of less ≥ 32 [byte] header + w vare rewrite processing is sing in progress vare data is damaged.	that this unit can receive. than windowSize can be received. indowSize + 8 (parameters other than firmData). is terminated normally.		
	windowSize numStatus = 1 Status ID Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status STAT_OK Firmw STAT_BUSY Proces STAT_INVALID_DATA Firmw ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic No parameter	of firmData Data) of less ≥ 32 [byte] header + w vare rewrite processing is sing in progress vare data is damaged.	that this unit can receive. than windowSize can be received. indowSize + 8 (parameters other than firmData). is terminated normally.		
	windowSize numStatus = 1 Status ID Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status STAT_OK Firmw STAT_BUSY Proces STAT_INVALID_DATA Firmw ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic	of firmData Data) of less ≥ 32 [byte] header + w vare rewrite processing is sing in progress vare data is damaged.	that this unit can receive. than windowSize can be received. indowSize + 8 (parameters other than firmData). is terminated normally.		
	windowSize numStatus = 1 Status ID Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status STAT_OK Firmw STAT_BUSY Proces STAT_INVALID_DATA Firmw ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic No parameter	of firmData Data) of less ≥ 32 [byte] header + w vare rewrite processing is sing in progress rare data is damaged.	that this unit can receive. than windowSize can be received. indowSize + 8 (parameters other than firmData). is terminated normally.		
	windowSize numStatus = 1 Status ID } ■ Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status STAT_OK Firmw STAT_BUSY Proces STAT_INVALID_DATA Firmw ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communication sequence error. No p	of firmData Data) of less ≥ 32 [byte] header + w vare rewrite processing is sing in progress vare data is damaged. cation protocol version	that this unit can receive. than windowSize can be received. indowSize + 8 (parameters other than firmData). is terminated normally.		
	windowSize numStatus = 1 Status ID } ■ Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status STAT_OK Firmw STAT_BUSY Proces STAT_INVALID_DATA Firmw ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communication sequence error. No p This cannot be accepted while an upd	of firmData Data) of less ≥ 32 [byte] header + w vare rewrite processing is sing in progress vare data is damaged. cation protocol version	that this unit can receive. than windowSize can be received. indowSize + 8 (parameters other than firmData). is terminated normally. set to a packet header.		
	windowSize numStatus = 1 Status ID ■ Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status STAT_OK Firmw STAT_BUSY Proces STAT_INVALID_DATA Firmw ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communication be used for the communication sequence error. No parameter ERR_SEQUENCE Communication sequence error. No parameter beautiful the communication sequence error.	of firmData Data) of less ≥ 32 [byte] header + w vare rewrite processing is sing in progress rare data is damaged. cation protocol version parameter. late mode is in operation	that this unit can receive. than windowSize can be received. indowSize + 8 (parameters other than firmData). is terminated normally. set to a packet header.		
	windowSize numStatus = 1 Status ID ■ Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status STAT_OK Firmw STAT_BUSY Proces STAT_INVALID_DATA Firmw ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communic No parameter ERR_SEQUENCE Communication sequence error. No p This cannot be accepted while an upd ERR_BIG This could not be received because page	of firmData Data) of less ≥ 32 [byte] header + w vare rewrite processing is sing in progress vare data is damaged. cation protocol version varameter. late mode is in operation cket size is too large.	that this unit can receive. than windowSize can be received. indowSize + 8 (parameters other than firmData). is terminated normally. set to a packet header. In and before rush conditions are confirmed.		
	windowSize numStatus = 1 Status ID ■ Meaning windowSize This is the size A packet (including firmI It is necessary to satisfy packetSize is Status ID Rewrite processing status STAT_OK Firmw STAT_BUSY Proces STAT_INVALID_DATA Firmw ERR_OK Firmware data was received normally. ERR_PROV This cannot be used for the communication be used for the communication sequence error. No parameter ERR_SEQUENCE Communication sequence error. No parameter beautiful the communication sequence error.	of firmData Data) of less ≥ 32 [byte] header + w vare rewrite processing sing in progress vare data is damaged. cation protocol version varameter. date mode is in operation cket size is too large. eceive buffer is insuffice	that this unit can receive. than windowSize can be received. indowSize + 8 (parameters other than firmData). is terminated normally. set to a packet header. In and before rush conditions are confirmed.		



Command	Description
CMD_WRITE_FIRM	ERR_INVALID_PARAM
	dataNo is invalid. (A value is skipped.) dataSize is invalid.
	Errors other than described above are errors in this unit.
	■ Remarks
CMD_COMPLETE	■ Outline
	This command notifies to confirm that firmware rewrite completion notification was accepted.
	■ Command parameter
	None
	■No response
	This unit is automatically restarted when this command is received.

Issuing the CMD_CHK_GUARD and CMD_WRITE_FIRM commands

■ Packet Header (Common in both a command and response)

Data arrangement	Size [Byte]	Туре
Packet Header{		
BodySize	4	uint
Protocol Version	2	uint
Command ID	2	uint
Response ID	2	uint
Sequence No.	2	uint
reserved	4	uint
reserved	4	uint
reserved	4	uint
reserved	8	uint
}		

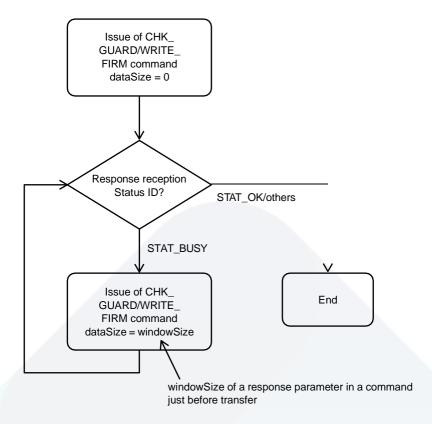
■ Command Parameter

Parameter data arrangement	Size [Byte]	Туре
CHK_GUARD Parameter{		
dataNo	4	uint
remainSize	2	uint
firmData	dataSize	Binary
}		

Parameter data arrangement	Size [Byte]	Туре
Response Parameter{		
windowSize	4	uint
numStatus	4	uint
for (i = 0; i < numStatus; i++){		
Status ID	2	uint
}		
}		

Firmware data is transferred from the host to the unit using CHK GUARD and WRITE_FIRM commands. For dataSize to be transferred, specify a value of less than windowSize set to the Response data that was issued just before transfer. When transmitting a command first, issue a command (with dataSize set to "0") without sending firmData and then issue a command for transferring data actually after confirming windowSize set to the Response data. Transmit data continuously until commands other than STAT_BUSY are returned.





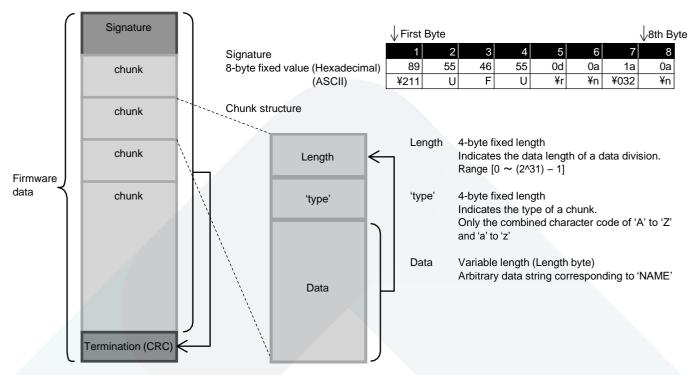
Discriminating the camera mode and updater mode

As described in the section of a UUD Firmware data structure, the USB PID, USB VID, and operating mode of equipment to be updated are described in the UDID chunk of firmware package data. The host to be updated confirms that USB PID and USB VID which acquired a USB descriptor from the unit are contained in the UDID chunk. By the ID operating mode, judge whether the unit is started in a camera mode or updater mode.



Structure of UUD Firmware data

- Signature is assigned to the top of data.
- One or more variable length chunk is continued after signature.
- A chunk containing a CRC32-calculated value is assigned to the termination of data.
- The byte order is based on a big-endian format. (MSB first)



Termination

Chunk indicating the termination data

The CRC-calculated value between the top of data (signature) and the chunk just before termination is stored.

For more details, see chunk list and detailed specifications. (page 66)



Chunk list and detailed specifications (Ver.1.0)

Description of type	
uint	Unsigned integer (Does not depend on the data length.)
Binary	Binary data string

DATV	Description						
	Version of firmware data structure						
	■ Limiting conditions						
	This necessarily exists as a chunk at the top.						
	■ Data arrangement						
	Arrangement	Size [Byte]	Туре	Value			
	DATV Chunk{						
	length	4	uint	0x00000004			
	type	4	uint	'DATV'			
	firmDataVersion	2	uint				
	reserved	2	uint				
	}						
	This indicates the protocol version of Fixed to 0x0100. reserved 0x0000	n user minware update.					
PROV	Fixed to 0x0100. reserved 0x0000 Communication protocol version of firm Limiting conditions This necessarily exists as the second chu	ware update					
PROV	Fixed to 0x0100. reserved 0x0000 Communication protocol version of firms Limiting conditions This necessarily exists as the second cha	ware update unk.	Туре	Value			
ROV	Fixed to 0x0100. reserved 0x0000 Communication protocol version of firm Limiting conditions This necessarily exists as the second chu	ware update	Туре	Value			
PROV	Fixed to 0x0100. reserved 0x0000 Communication protocol version of firms Limiting conditions This necessarily exists as the second chu Data arrangement Arrangement	ware update unk.	Type uint	Value 0x00000004			
PROV	Fixed to 0x0100. reserved 0x0000 Communication protocol version of firms Limiting conditions This necessarily exists as the second chu Data arrangement Arrangement PROV Chunk {	ware update unk. Size [Byte]					
PROV	Fixed to 0x0100. reserved 0x0000 Communication protocol version of firm Limiting conditions This necessarily exists as the second chu Data arrangement Arrangement PROV Chunk{ length	ware update unk. Size [Byte]	uint	0x00000004			
ROV	Fixed to 0x0100. reserved 0x0000 Communication protocol version of firms Limiting conditions This necessarily exists as the second cha Data arrangement Arrangement PROV Chunk{ length type	ware update unk. Size [Byte] 4 4	uint uint	0x00000004			



	Description						
UDID	List of PID and VID corresponding to this unit to be updated in firmware						
	■ Limiting conditions						
	This necessarily exists as a chunk.						
	■ Data arrangement						
	Arrangement	Size [Byte]	Туре	Value			
	UDID Chunk{	5.25[2765]	- 7	1			
	length	4	uint	4+id_count*8			
	type	4	uint	'UDID'			
	id_count	4	uint	0212			
	/* Descriptor ID List */		GIII				
	for (i=0; i < id_count; i++){						
	PID	2	ID				
	VID	2	ID				
	Operating mode	1	uint				
	reserved = 0	3	uint	0x000000			
	}						
	}						
	■ Meaning						
	id_count						
	This is the number of lists in the corr	esponding VID and PID.					
	PID						
	This is the corresponding PID.						
	VID						
	This is the corresponding VID.						
	Operating			mode			
	This is information for identifying w	hether PID and VID are us	ed during application	n operation of a main set or			
	during updater mode operation.						
	ID during application operation of a r	main set: 0x01					
	ID during updater operation:	0x02					
FDAT	Firmware data						
	■ Limiting conditions						
	This necessarily exists as a chunk.						
	Data arrangement	Size [Byte]	Type	Value			
	■ Data arrangement Arrangement	Size [Byte]	Туре	Value			
	■ Data arrangement Arrangement FDAT Chunk{			Value			
	■ Data arrangement Arrangement FDAT Chunk{ length	4	uint				
	■ Data arrangement Arrangement FDAT Chunk{ length type	4 4	uint uint	Value 'FDAT'			
	■ Data arrangement Arrangement FDAT Chunk{ length	4	uint				
	■ Data arrangement Arrangement FDAT Chunk{ length type	4 4	uint uint				
	■ Data arrangement Arrangement FDAT Chunk{ length type	4 4	uint uint				
	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data }	4 4	uint uint				
DEND	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data } ■ Meaning Firmware data	4 4	uint uint				
DEND	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data } ■ Meaning Firmware data Chunk indicating the termination of data	4 4	uint uint				
DEND	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data } ■ Meaning Firmware data Chunk indicating the termination of data ■ Limiting conditions	4 4	uint uint				
DEND	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data } ■ Meaning Firmware data Chunk indicating the termination of data ■ Limiting conditions This necessarily exists as a chunk.	4 4 length	uint uint				
DEND	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data } ■ Meaning Firmware data Chunk indicating the termination of data ■ Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ignore	4 4 length	uint uint				
DEND	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data } ■ Meaning Firmware data Chunk indicating the termination of data ■ Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ignore ■ Data arrangement	4 4 length	uint uint Binary	'FDAT'			
DEND	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data } ■ Meaning Firmware data Chunk indicating the termination of data ■ Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ignore ■ Data arrangement Arrangement	4 4 length	uint uint				
DEND	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data } ■ Meaning Firmware data Chunk indicating the termination of data ■ Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ignore ■ Data arrangement Arrangement DEND Chunk{	4 4 length ed.	uint uint Binary	'FDAT'			
DEND	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data } ■ Meaning Firmware data Chunk indicating the termination of data ■ Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ignore ■ Data arrangement Arrangement DEND Chunk{ length	ed. Size [Byte]	uint uint Binary Type	'FDAT'			
DEND	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data } ■ Meaning Firmware data Chunk indicating the termination of data ■ Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ignore ■ Data arrangement Arrangement DEND Chunk{ length type	ed. Size [Byte] 4 4 4 1ength	uint uint Binary Type uint uint	'FDAT'			
DEND	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data } ■ Meaning Firmware data Chunk indicating the termination of data ■ Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ignore ■ Data arrangement Arrangement DEND Chunk{ length	ed. Size [Byte]	uint uint Binary Type	'FDAT'			
DEND	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data } ■ Meaning Firmware data Chunk indicating the termination of data ■ Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ignore ■ Data arrangement Arrangement DEND Chunk{ length type	ed. Size [Byte] 4 4 4 1ength	uint uint Binary Type uint uint	'FDAT'			
DEND	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data } ■ Meaning Firmware data Chunk indicating the termination of data ■ Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ignore ■ Data arrangement Arrangement DEND Chunk{ length type CRC }	ed. Size [Byte] 4 4 4 1ength	uint uint Binary Type uint uint	'FDAT'			
DEND	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data } ■ Meaning Firmware data Chunk indicating the termination of data ■ Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ignore ■ Data arrangement Arrangement DEND Chunk{ length type CRC } ■ Meaning	ed. Size [Byte] 4 4 4 1ength	uint uint Binary Type uint uint	'FDAT'			
DEND	■ Data arrangement Arrangement FDAT Chunk{ length type Firmware data } ■ Meaning Firmware data Chunk indicating the termination of data ■ Limiting conditions This necessarily exists as a chunk. The data stream after this chunk is ignore ■ Data arrangement Arrangement DEND Chunk{ length type CRC }	ed. Size [Byte] 4 4 4 1ength	uint uint Binary Type uint uint uint uint uint	'FDAT' Value 'DEND'			



Specifications

Imager 1/2.5 Type "Exmor R" CMOS Sensor

Picture elements 8510K pixels Lens 20× Zoom

f = 4.4 mm (Wide), 88.0 mm (Tele),

F2.0 to F3.8

Zoom movement speed
Optical Wide – Optical Tele
3.0 sec (Focus Tracking On)
Optical Wide – Super resolution

zoom Tele 3.4 sec

Digital Wide – Digital zoom Tele

5.0 sec

Focus Movement time

 ∞ to Near 0.1 sec

Digital zoom $12 \times (240 \times \text{ with optical zoom})$

Angle of view (H)

Approx. 70.2 degrees (Wide end,

Image stabilizer Off)

Approx. 4.1 degrees (Tele end, Image

stabilizer Off)

Approx. 60.0 degrees (Wide end,

Image stabilizer On)

Approx. 3.5 degrees (Tele end, Image

stabilizer On)

Min. working distance

80 mm (Wide end), 800 mm (Tele

end)

Min. illumination

(Typical) 0.4 lx (1/30 sec, 50%, High

Sensitivity mode On) 1.6 lx (1/30 sec, 50%, High Sensitivity mode Off)

0.06 lx (1/4 sec (1/3 sec), 50%, High

Sensitivity mode On)

0.21 lx (1/4 sec (1/3 sec), 50%, High

Sensitivity mode Off)

Sync system Internal/External (only FCB-ER8550)

Recommended illumination

100 lx to 100,000 lx

S/N ratio 50 dB (Weight On)

Back light compensation

On/Off

Electronic shutter speed

1/1 sec to 1/10000 sec (28 steps)

White Balance Auto, ATW, Indoor, Outdoor, One

Push WB, Manual WB, Outdoor Auto, Sodium Vapor Lamp (Fix/

Auto/Outdoor Auto)

Gain Auto/Manual (0 to 48 dB (0 to 16

step))

Max. Gain Limit (9 to 48 dB (3 to 12

step))

Noise Reduction On/Off (level 5 to 1 / Off, 6 steps)

Defog mode On/Off (Low, Mid, High)

Aperture control 16 steps

Preset 16-POSITIONS

Camera control IF

VISCA protocol (CMOS 3.1V) PTP USB 9.6 kbps, 19.2 kbps, 38.4 kbps, 115.2 kbps, Stop bit,

1 bit

Video Output Digital (HDMI)

Storage temperature/Humidity

 $-20 \,^{\circ}\text{C}$ to $+60 \,^{\circ}\text{C}$ ($-4 \,^{\circ}\text{F}$ to $+140 \,^{\circ}\text{F}$)/

20% to 95%

Absolute humidity: 36 g/m³

Operating temperature/Humidity

-5 °C to +60 °C (23 °F to 140 °F)/

20% to 80%

Absolute humidity: 36 g/m³

Power requirements

6 V to 12 V DC

Power consumption

3.0 W (When the motor operates:

4.0 W)

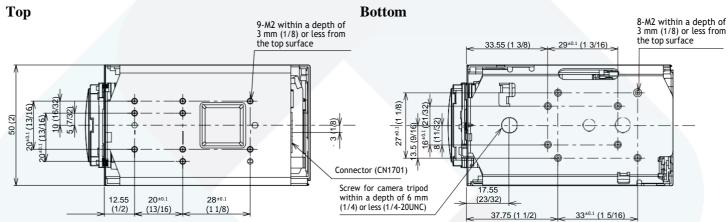
Mass Approx. 275 g (10 oz.) Dimensions $50 \times 60 \times 93.3$ mm

 $(2 \times 2^{3}/8 \times 3^{3}/4 \text{ in.}) \text{ (w/h/d)}$

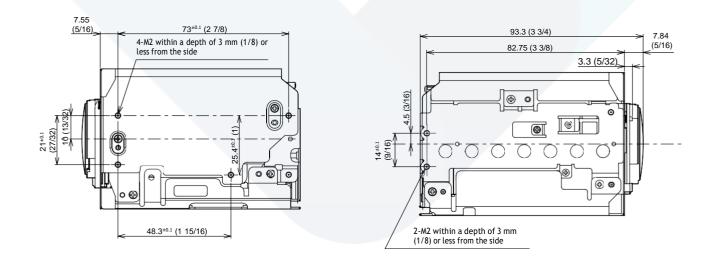


Dimensions

Front Back | 17.6 | 25 (1) | 17.6 | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32) | (23/32)



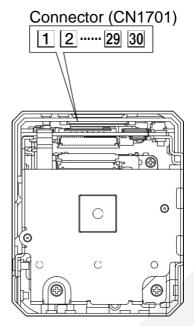
Left side Right side



Unit: mm (inches)



Pin assignment



CN1701

KEL Co. USL00-30L-C

Pin No.	I/O	Name	Level
1	-/-	GND	Ecvei
2	0	TMDS Clock -	
3	0	TMDS Clock +	
4	_	GND	
5	0	TMDS Data 0 -	
6	0	TMDS Data 0 +	
7		GND	
8	0	TMDS Data 1 -	
9	0	TMDS Data 1 +	
10	_	GND	
11	О	TMDS Data 2 -	
12	О	TMDS Data 2 +	
13		GND	
14	О	XSD0_ACC_LED	Only FCB-ER8550
15	I	EXT_SYNC	Only FCB-ER8550
16	О	EXT_SYNC_LOCK	Only FCB-ER8550
17	I	Hot Plug Detect	TMDS Out: 5V DC
			TMDS Stop: Open or GND
18	О	+ 5V Power	
19	I	USB_VBUS	USB communication active:
		_	5 V DC
			USB communication
			inactive: Open or GND
20		GND	macurer open of or the
21	I/O	USB D -	
22	I/O	USB_D +	
23	1/0	GND	
24	I	VISCA RxD	CMOC 2 1V
2-7	1	VISCH_KAD	CMOS 3.1V
			(High: Min 2.3 [V],
			Low: Max 1.0 [V])
25	О	VISCA_TxD	CMOS 3.1V
			(High: Min 2.7 [V],
			Low: Max 0.4 [V])
26	I	RESET	Reset operation: Low (GND)
			Reset cancel: Open (High
			Impedance)
27	I	DC IN	6 to 12 V DC
28	I	DC IN	6 to 12 V DC
29	I	DC IN	6 to 12 V DC
30	I	DC IN	6 to 12 V DC

^{*} It is assumed that Pin No. 18 is used as the 5 V power supply of HDMI.

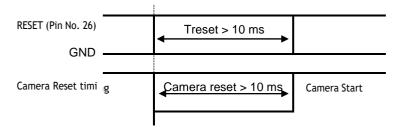
If you cannot prepare VBUS, connect Pin No. 18 to Pin No. 19.



^{*} When you use the USB communication, connect VBUS of the USB host to Pin No. 19.

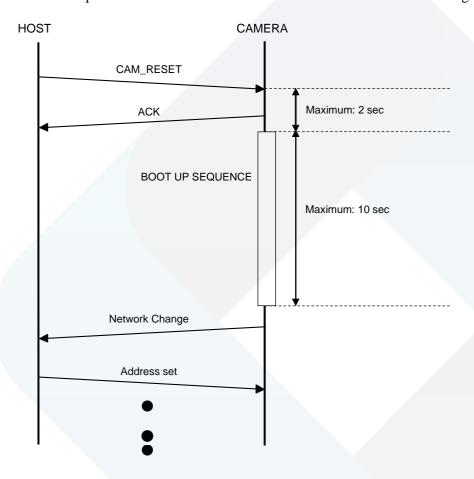
Reset Timing Specification

Low level (GND) pulse (whose width is 10 ms or more) resets this camera.



Reset by Visca command

The time required from the end of camera reset to the issue of Network Change is as shown below.





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[openssl]

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[pcre]

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The basic library functions are written in C and are freestanding. Also included in the distribution is a set of C++ wrapper functions.

THE BASIC LIBRARY FUNCTIONS

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[zlib]

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