

## DATASENSING VISION SENSOR DATAVS2 REID

DATAVS2-06-REID  
 Vision Sensor, 6mm lens, ID, Red LED

- Controls for bar code, Datamatrix and OCV
- Memory for up to 20 different inspections
- 3 outputs
- R232 interface



### PRODUCT DESCRIPTION

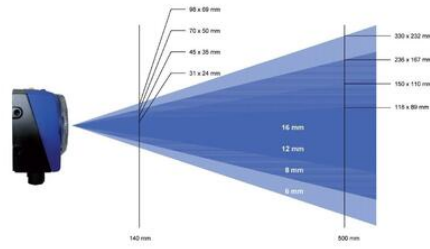
DataVS2 is a series of Vision sensors for flexible solutions for machine applications.

The sensor is complete with optics, red LED lighting and electronics in a compact housing. The parameters in the sensor are set via PC through Ethernet communication. The software comes with the sensor and is developed to lead the user step by step through parameter setting. DataVS2 is available in 4 different versions with different control instruments.

Identification ID - Reads bar codes, datamatrix and OCV.

### TECHNICAL DATA

<b>Digital interface</b>	Ethernet 10/100 Mbs (4-pole M12 -connector)
<b>Electrical connection</b>	M12 4-pole D-coded, M12 8-pin connector
<b>Frame rate</b>	60
<b>IP class</b>	IP50
<b>Lens material</b>	ABS plastic
<b>Material protection</b>	Aluminium
<b>Optics</b>	6mm integrated lens
<b>Output</b>	3xPNP, RS232
<b>Output current max</b>	0.1 A
<b>Power consumption max</b>	0.1 A
<b>Temperature operational max</b>	50 °C
<b>Temperature operational min</b>	-10 °C
<b>Voltage dc max</b>	24 V
<b>Voltage dc min</b>	24 V



M12 4-pole Ethernet

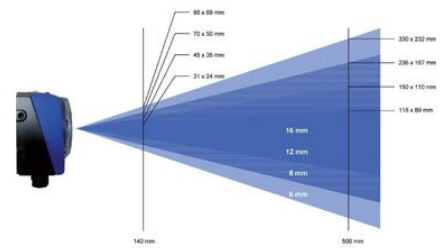
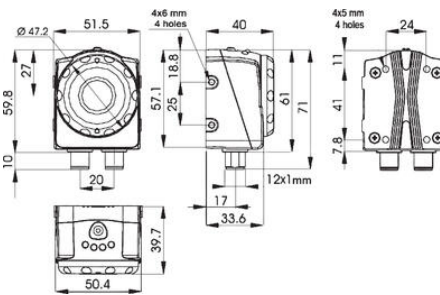


M12 8-pole (power supply and IO)



- OBJ and AOR models**
- 1 = white = digital input 1
  - 2 = brown = 24 VDC
  - 3 = green = configurable output
  - 4 = yellow = output 1
  - 5 = grey = output 2
  - 6 = pink = output 3
  - 7 = blue = GND
  - 8 = red = external trigger
- ID and PRO models**
- 1 = white = RS232 RX
  - 2 = brown = 24 VDC
  - 3 = green = configurable output
  - 4 = yellow = output 1
  - 5 = grey = output 2
  - 6 = pink = RS232 TX
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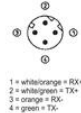
- Step 1: Image Setup**
- The first step consists in connecting the sensor and configuring the image quality parameters. When the desired results are obtained, the user can memorise the image that will be used as a template during sensor functioning.
- Step 2: Teach**
- The second step establishes the acceptance criteria to distinguish objects from wastes. One or more controls can be selected according to the task to carry out.
- Step 3: Run**
- The third step configures the sensor digital outputs, simulates sensor functioning on the PC to verify the controls chosen and activates the operating phase on the sensor using the PC only to control the diagnostics.



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